



 **Wright State University** 

EE480/680
Micro-Electro-Mechanical Systems (MEMS)
Summer 2006





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Transducers: Sensors

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 **Overview** 

- Piezoelectric
- Piezoresistive
- Thermoresistive
- Capacitive
- Other
- Microelectronics and MEMS

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 **Sensors** 

- A good reference for sensor interface circuits:
 - J. W. Gardner, *Microsensors Principles and Applications*, John Wiley & Sons Ltd, 1994, ISBN 0-471-94136-0.

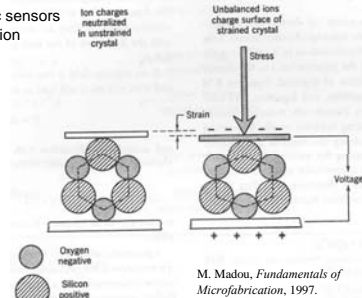
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Sensors: Piezoelectric



- A piezoelectric material induces a charge or develops a voltage across itself when deformed
 - Anisotropic behavior
 - High Q - Low Damping
 - Offset, temperature effects, parasitic currents limit operation to AC > 5 Hz - DC operation impractical
 - High output impedance makes piezoelectric sensors sensitive to load and electromagnetic radiation
 - Small displacement output



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Sensors: Piezoelectric



Table 7.14 Piezoelectric coefficients of materials at 300 K.

Material	Type	Form	Coefficient, Ξ_{31} (pC/N)	Permittivity, ϵ_r
Quartz (X-cut)	Glass	Bulk	2.33	4.0
PVDF	Polymer	Film	1.59	-
P(VDF-TrFE)	Polymer	Film	18.0	6.2
ZnO	Ceramic	Bulk	11.7	9.0
ZnO	Ceramic	Film	12.4	10.3
BaTiO ₃	Ceramic	Bulk	190	4,100
PZT	Ceramic	Bulk	370	300-3,000

J. W. Gardner, *Microsensors: Principles and Applications*, 1994

PbZrTiO₃ (PZT) can also be deposited as a thin film

$$q = \Xi F$$

$$q = CV$$

$$C = \frac{\epsilon_0 \epsilon_r A}{x_0}$$

$$V = \frac{\Xi F x_0}{\epsilon_0 \epsilon_r A}$$

$$\epsilon = \Xi H$$

(applied voltage)

$$\epsilon = \frac{x - x_0}{x_0} = \frac{\Delta x}{x_0}$$

$$H = \frac{V}{x_0}$$

$$\Delta x = \Xi V$$

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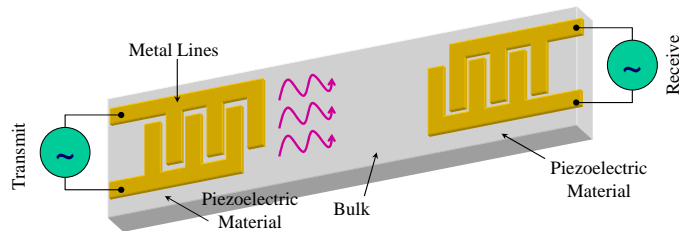
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Sensors: Piezoelectric



- Ex. Surface Acoustic Wave (SAW) device
 - Generates surface waves (30 MHz - 1 GHz)
 - Senses surface waves
 - Phase and/or frequency of the sensed wave is changed while traveling through the bulk
 - Anything that changes the bulk will affect the phase and/or frequency
 - temperature, chemicals, vibration, strain, viscosity, density, etc.



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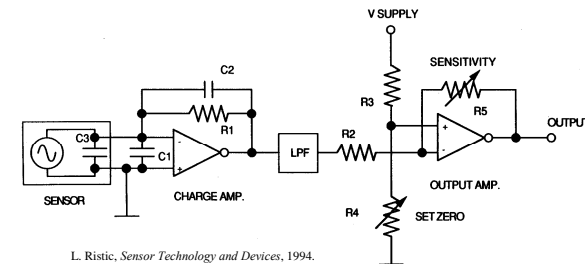
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Sensors: Piezoelectric



- A piezoelectric charge amplification circuit



Piezoelectric devices include actuators, temperature sensors, pressure sensors, accelerometers, ultrasound transducers, etc.

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Sensors: Piezoresistive



- Piezoresistance is when a material's resistance changes when the material is stressed.

- Anisotropic behavior
- Temperature sensitive

$$\frac{\Delta R}{R} = \sigma_l \pi_l + \sigma_t \pi_t$$

Ex. For the longitudinal direction of $\langle 110 \rangle$, the longitudinal (l) and transverse (t) coefficients are:

$$\pi_l = \frac{1}{2}(\pi_{11} + \pi_{12} + \pi_{44})$$

$$\pi_t = \frac{1}{2}(\pi_{11} + \pi_{12} - \pi_{44})$$

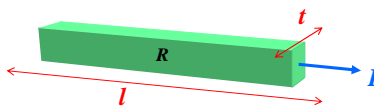


TABLE 4.5 Resistivity and Piezoresistance at Room Temperature^{25,49}

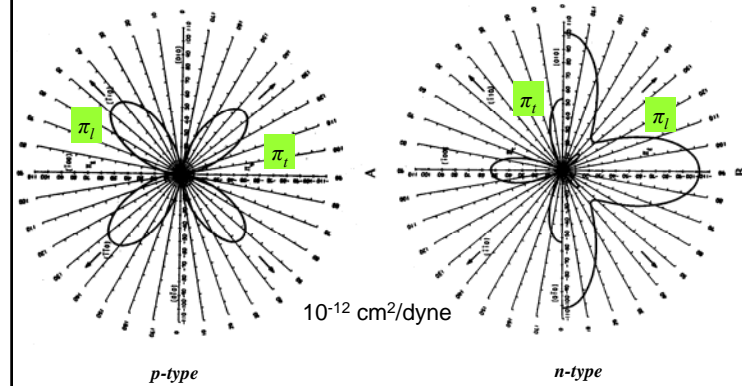
	ρ (Ω cm)	π_{11}^a	π_{12}^a	π_{44}^a
p-Si	7.8	+6.6	-1.1	+138.1
n-Si	11.7	-102.2	+53.4	-13.6

^a Expressed in 10^{-12} cm² dyne⁻¹ or 10^{-11} Pa⁻¹.

M. Madou, *Fundamentals of Microfabrication*, 1997.



Sensors: Piezoresistive



M. Madou, *Fundamentals of Microfabrication*, 1997.



Sensors: Piezoresistive



- Ex. Motorola Manifold-Absolute-Pressure (MAP) Sensor "Xducer" **20 μ m thick membrane**
 - Piezoresistor oriented to take advantage of π_{44}
 - Differential voltage sensed between S+ and S-.

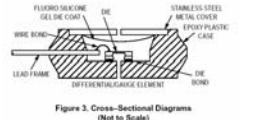
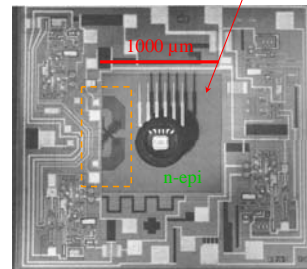
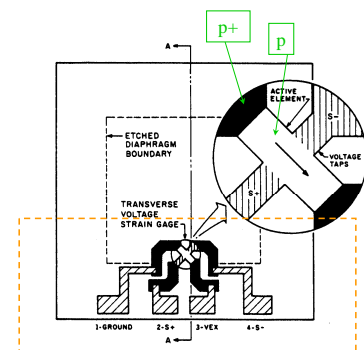


Figure 3. Cross-Sectional Diagrams (Not to Scale)



Sensors: Thermoresistive



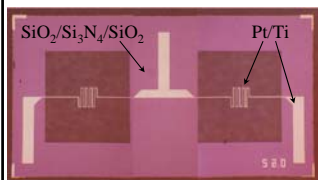
- This type of sensing takes advantage of the fact that resistance varies with temperature.
- A linear approximation:
 - $R = R_0[1 + \alpha_R(T - T_0)]$
- α_R is the Temperature Coefficient of Resistance (TCR)
 - Platinum: $\alpha_R = 3.9 \times 10^{-4} \text{ K}^{-1}$
 - n-Si: $\alpha_R = 2.5 \times 10^{-3} \text{ K}^{-1}$



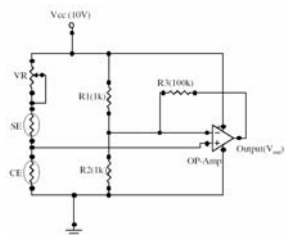
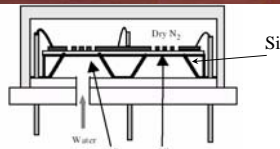
Sensors: Thermoresistive



- Ex. Humidity Sensor
 - D. H. Lee et al., "A Micromachined Robust Humidity Sensor for Harsh Environment Applications, 2001.



Pt resistors are self heated to 350 °C, as humidity increases, resistor cools, thereby reducing resistance.



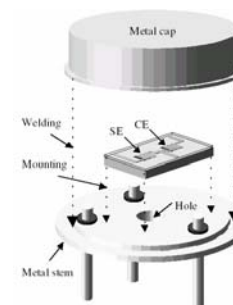
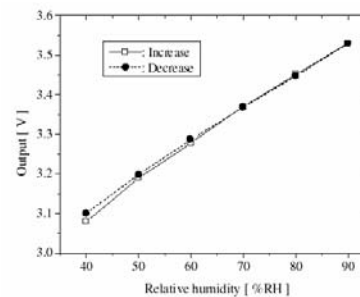
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Sensors: Thermoresistive



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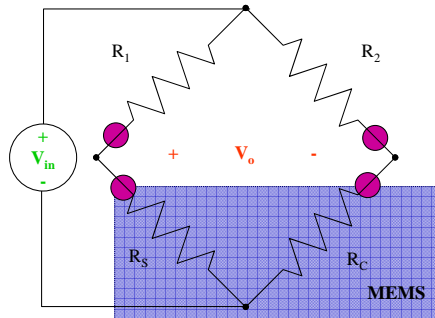
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Sensors: Change in Resistance



- Don't forget the Wheatstone Bridge



Typically:
 R_S = MEMS sensor
 R_C = MEMS compensation sensor
 R_1 & R_2 = External bias or MEMS resistors
 ● = Trim resistor locations

$$\frac{dV_o}{dR_S} = \frac{R_1 V_{in}}{(R_1 + R_S)^2}$$

Sensitivity greatest when $R_1 = R_S$

Trimming is done by variable resistors off-chip and/or by physical modification of MEMS sensors, i.e. laser ablation of resistor material.

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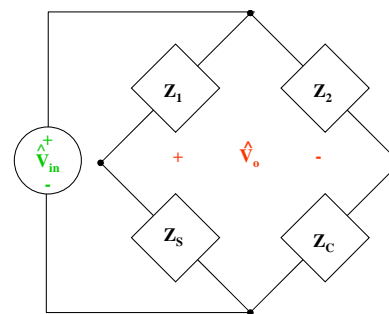
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Sensors: Change in Impedance



- Furthermore, the Wheatstone Bridge ain't just for resistors anymore ... phasor analysis:



$$\hat{V}_{in} = P\{V_{in} \cos(\omega t + \phi)\} = V_{in} e^{j\phi}$$

$$Z_{cap} = 1/C\omega j$$

$$Z_{ind} = L\omega j$$

$$Z_{res} = R$$

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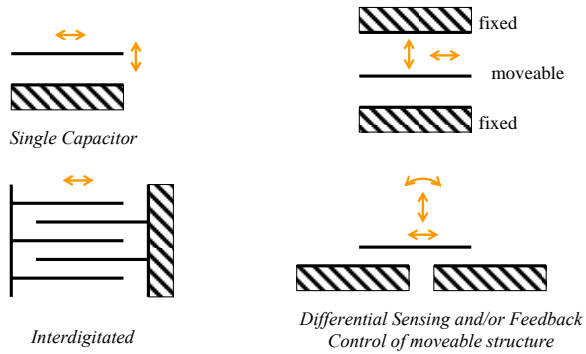
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Sensors: Capacitive



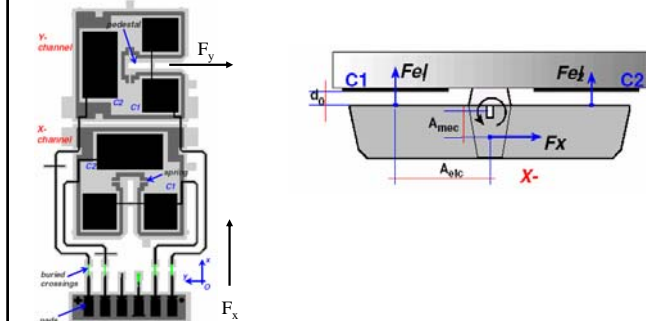
- MEMS structures can be viewed as arrangements of capacitors:



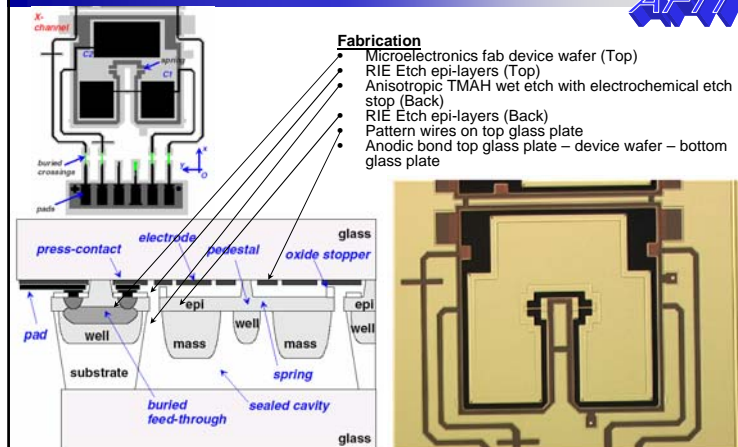
Sensors: Capacitive



- Ex. Accelerometer
 - D. Lapadatu et al., "Dual-axes Capacitive Inclinometer / Low-g Accelerometer for Automotive Applications," 2001.



Sensors: Capacitive



Sensors: Other



- Inductive
- Magnetic



Microelectronics and MEMS



- For the most part, MEMS are fabricated using the same techniques, materials, and chemicals as microelectronics.
- Can MEMS and Microelectronics be integrated?
 - Major characteristics of microelectronic structures:
 - Crystalline semiconductor substrates; p or n-wells; and crystalline, polycrystalline, or amorphous thin films
 - Major characteristics of MEMS structures:
 - Crystalline semiconductor materials - *Bulk Micromachining*
 - Polycrystalline and Amorphous semiconductor and non-semiconductor materials - *Surface Micromachining*
 - Electroplated metals, polymers, etc. - *Micromolding*
- The combination of MEMS and Microelectronics is usually referred to as:

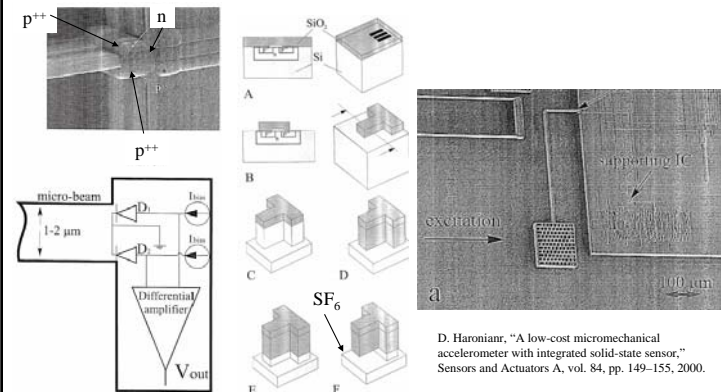
“INTEGRATION”



Integration: Bulk Etched CMOS



- Post RIE patterning and isotropic Si etch to release bulk structures:



Integration: Bulk Etched CMOS



- Si bulk etch from “back” of CMOS chip:
ex. Motorola

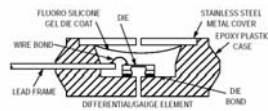
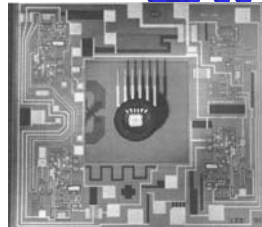
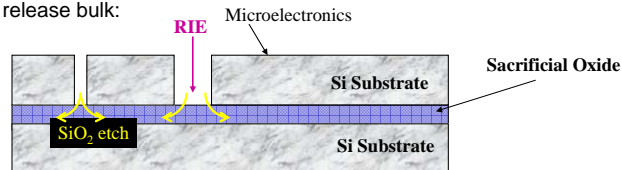


Figure 3. Cross-Sectional Diagrams (Not to Scale)



- Post RIE patterning and SiO₂ etch of SOI to release bulk:

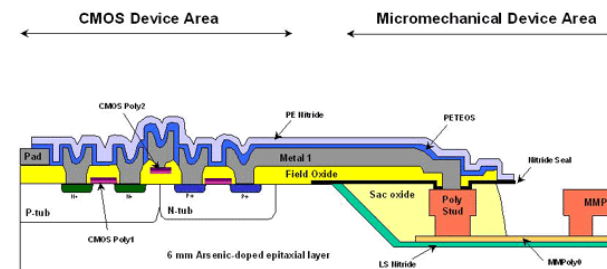


Integration: Trench Integration



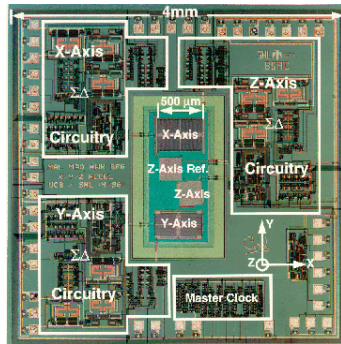
- Sandia's Integrated MicroElectroMechanical Systems (IMEMS)
 - A fabrication process that enables both CMOS circuitry and surface micromachined MEMS to be created on the same chip.

SNL Integrated Micromechanical / CMOS



Integration: Trench Integration

- Ex. Three-axis, force-balanced accelerometer - designed by Berkely Sensor and Actuator Center (BSAC) at U.C. Berkeley



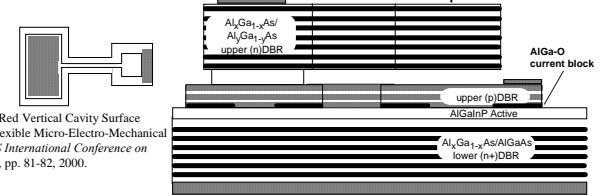
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Integration: III-V Thin Films

- Sacrificial etching of III-V materials yields inherent combination of electronics and mechanical structures
 - 95:1 GaAs to AlGaAs with 10:1 ratio of citric acid $\{C_6H_8O_7\}$ (50%) : hydrogen peroxide $\{H_2O_2\}$ (30%) - Kovacs
 - GaAs etch with mixture of $C_6H_8O_7$, $K_3CH_5O_2$, H_2O_2 - Raley



J. A. Lott et al., "Tunable Red Vertical Cavity Surface Emitting Lasers Using Flexible Micro-Electro-Mechanical Top Mirrors," *IEEE/LEOS International Conference on Optical MEMS*, Kauai, HI, pp. 81-82, 2000.

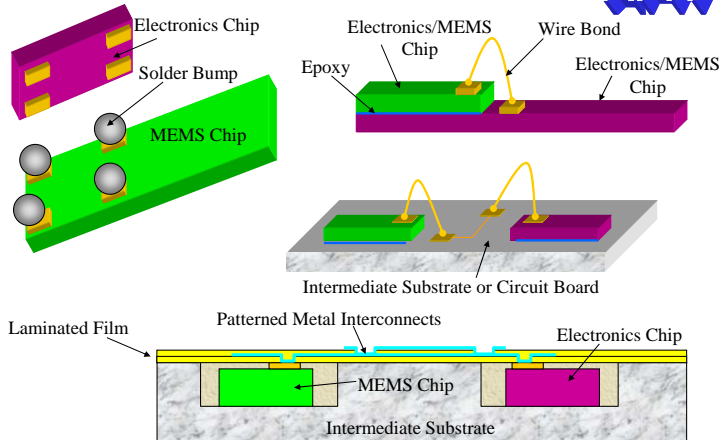
- Sacrificial etch for Epi-Si systems?
- Polysilicon electronic devices?

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Integration: Multi-Chip Arrangement



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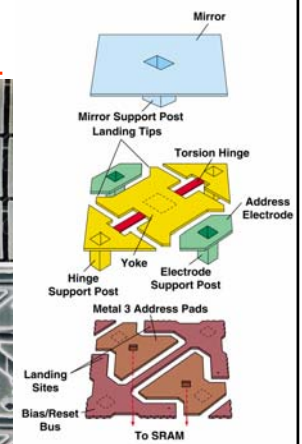
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Integration: Surface Micromachining on microelectronics

- Parallel Plate Examples: Texas Instruments Digital Micromirror Device™



SXGA device with black aperture: 1280x1024; 1,310,720 mirrors



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