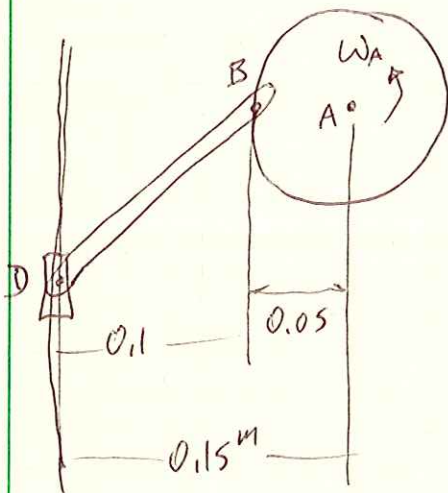


PROB. 16-126

$$L = 0.25 \text{ m}, \quad m = 5 \text{ kg}, \quad \omega_A = 52.36 \frac{\text{RAD}}{\text{s}}$$

FIND  $\vec{D}$  WHEN  $\theta = 90^\circ$



KINEMATICS

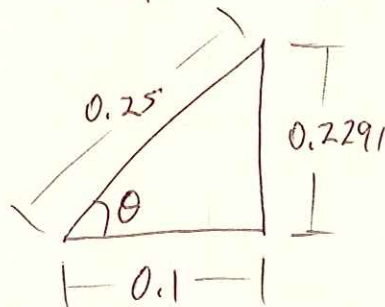
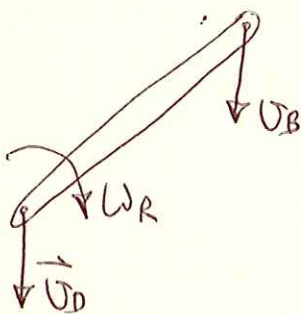
$$\vec{v}_B = \omega_A \hat{k} \times \vec{r}_{AB}$$

$$\vec{v}_B = - (52.36 \frac{\text{RAD}}{\text{s}}) (0.05 \text{ m}) \hat{j} = (-2.618) \hat{j} \frac{\text{m}}{\text{s}}$$

$$\vec{v}_D = (-v_D) \hat{j}$$

$$\vec{v}_B = \vec{v}_D + \vec{v}_{B/D}$$

$$\vec{v}_{B/D} = \omega_R \hat{k} \times \vec{r}_{DB}$$



$$\theta = \cos^{-1} \left( \frac{0.1}{0.25} \right)$$

$$\theta = 66.42^\circ$$

$$\vec{r}_{DB} = (0.25 \text{ m}) [(\cos 66.42^\circ) \hat{i} + (\sin 66.42^\circ) \hat{j}]$$

$$\vec{r}_{DB} = (0.1) \hat{i} + (0.2291) \hat{j} \text{ m}$$

$$\vec{v}_{B/D} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & \omega_R \\ 0.1 & 0.2291 & 0 \end{vmatrix}$$

$$= (0 - 0.2291 \omega_R) \hat{i} - (0 - 0.1 \omega_R) \hat{j}$$

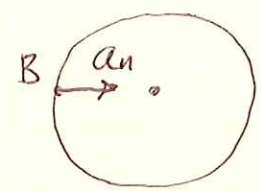
$$= (-0.2291 \omega_R) \hat{i} + (0.1 \omega_R) \hat{j} \frac{\text{m}}{\text{s}}$$

PROB. 16-126 CONT.

$$(-2.618)\hat{j} = (-\omega_D)\hat{j} + (-0.2291\omega_R)\hat{i} + (0.11\omega_R)\hat{j}$$

X-DIRECTION:  $\boxed{\omega_R = 0}$

$$\vec{a}_B = \alpha_A \hat{k} \times \vec{r}_{AB} - \omega_A^2 \vec{r}_{AB} = (\omega_A^2 r_{AB}) \hat{i}$$



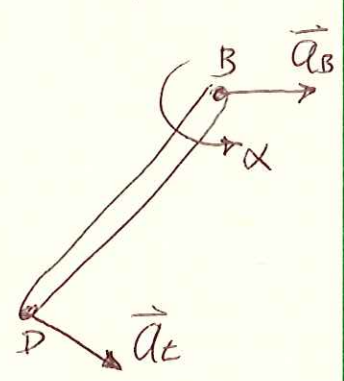
$$\vec{a}_B = \left[ (52.36 \frac{\text{RAD}}{\text{s}})^2 (0.05 \text{m}) \right] \hat{i} = (137.1) \hat{i} \frac{\text{M}}{\text{s}^2}$$

$$\vec{a}_D = (a_D) \hat{j}$$

$$\vec{a}_D = \vec{a}_B + \vec{a}_{D/B} = \vec{a}_B + \vec{a}_t + \vec{a}_n \quad \text{SINCE } \omega_R = 0$$

$$\vec{a}_t = \alpha \hat{k} \times \vec{r}_{BD}$$

$$\vec{r}_{BD} = -\vec{r}_{DB} = (-0.1) \hat{i} + (-0.2291) \hat{j} \text{ m}$$



$$\vec{a}_t = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & \alpha \\ -0.1 & -0.2291 & 0 \end{vmatrix}$$

$$= [0 - (-0.2291)\alpha] \hat{i} - [0 - (-0.1)\alpha] \hat{j}$$

$$\vec{a}_t = (0.2291\alpha) \hat{i} + (-0.1\alpha) \hat{j} \frac{\text{M}}{\text{s}^2}$$

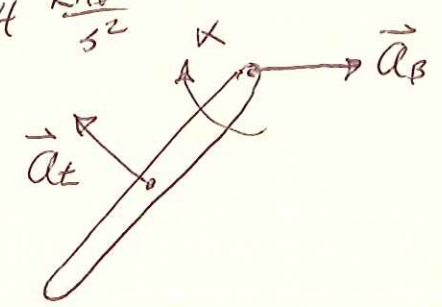
$$(a_D) \hat{j} = (137.1) \hat{i} + (0.2291\alpha) \hat{i} + (-0.1\alpha) \hat{j}$$

X-DIRECTION:

$$0 = 137.1 + 0.2291\alpha \Rightarrow \alpha = -598.4 \frac{\text{RAD}}{\text{s}^2}$$

ACCELERATION OF POINT G:

$$\vec{a}_G = \vec{a}_B + \vec{a}_{G/B}$$



PROB. 16-126 CONT

$$\vec{a}_{G/B} = \vec{a}_E + \vec{a}_n = \alpha \hat{k} \times \vec{r}_{BG} - \omega_R^2 \vec{r}_{BG}$$

$$\vec{r}_{BG} = \frac{1}{2} \vec{r}_{BD} = (-0.05) \hat{i} + (-0.1145) \hat{j} \text{ m}$$

$$\vec{a}_{G/B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & -598.4 \\ -0.05 & -0.1145 & 0 \end{vmatrix}$$

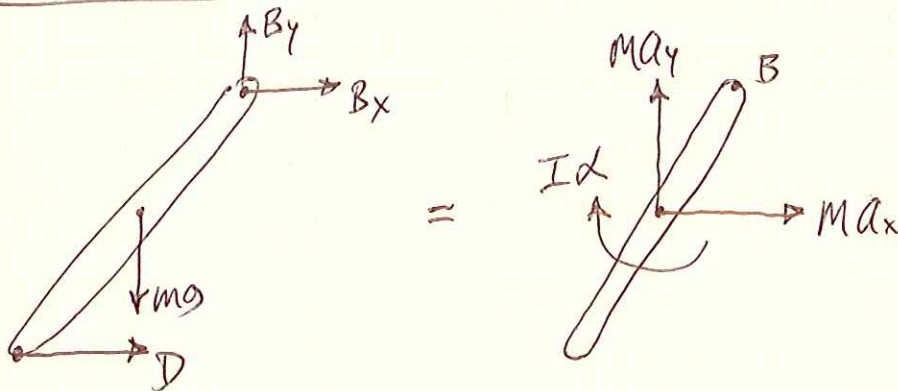
$$\vec{a}_{G/B} = [0 - (-598.4)(-0.1145)] \hat{i} - [0 - (-598.4)(-0.05)] \hat{j}$$

$$\vec{a}_{G/B} = (-68.55) \hat{i} + (29.92) \hat{j} \frac{\text{m}}{\text{s}^2}$$

$$\vec{a}_G = (137.1) \hat{i} + (-68.55) \hat{i} + (29.92) \hat{j}$$

$$\vec{a}_G = (68.55) \hat{i} + (29.92) \hat{j} \frac{\text{m}}{\text{s}^2}$$

KINETICS



$$\Sigma M_B = \Sigma (M_B)_{\text{EFF}} \quad \uparrow \curvearrowright : (0.2291 \text{ m}) D + (0.05 \text{ m}) (5 \text{ kg}) (9.81 \frac{\text{m}}{\text{s}^2})$$

$$= (0.1145 \text{ m}) (5 \text{ kg}) (68.55 \frac{\text{m}}{\text{s}^2}) - (0.05 \text{ m}) (5 \text{ kg}) (29.92 \frac{\text{m}}{\text{s}^2})$$

$$- \frac{1}{12} (5 \text{ kg}) (0.25 \text{ m})^2 (598.4 \frac{\text{RAD}}{\text{s}^2}) \quad \boxed{D = 59.92 \text{ N}}$$