

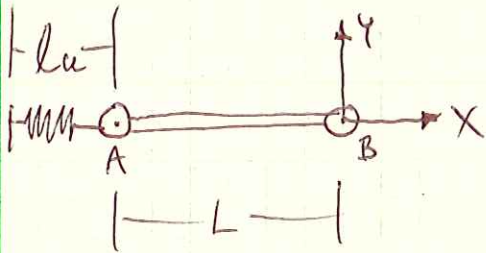
PROB. 17-38

$$W = 9 \text{ LB}, \quad K = \left(3 \frac{\text{LB}}{\text{IN}}\right) \left(\frac{12 \text{ IN}}{\text{ft}}\right) = 36 \frac{\text{LB}}{\text{ft}}, \quad L = \frac{25}{12} \text{ ft},$$

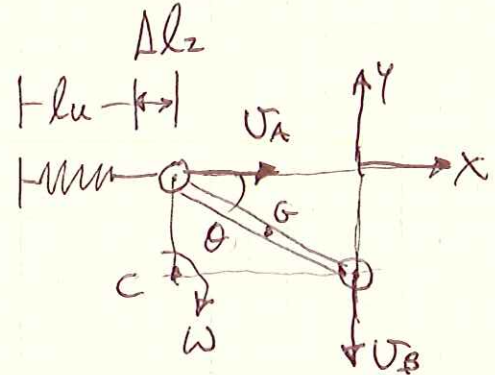
$L_s = l_u$ WHEN $\theta = 0$, $v = 0$ WHEN $\theta = 0$,

FIND ω AND v_B WHEN $\theta = 30^\circ$.

POSITION 1



POSITION 2



CONSERVATION OF ENERGY:

$$T_1 + (V_e)_1 + (V_g)_1 = T_2 + (V_e)_2 + (V_g)_2$$

$$T_1 = 0, \quad (V_e)_1 = 0, \quad (V_g)_1 = 0$$

$$T_2 = \frac{1}{2} m \bar{v}^2 + \frac{1}{2} \bar{I} \omega^2$$

$$\bar{v} = v \omega = \frac{1}{2} L \omega, \quad \bar{I} = \frac{1}{12} m L^2$$

$$T_2 = \frac{1}{2} m \left(\frac{1}{2} L \omega\right)^2 + \frac{1}{2} \left(\frac{1}{12} m L^2\right) \omega^2 = \frac{1}{6} m L^2 \omega^2$$

$$(V_e)_2 = \frac{1}{2} K (\Delta l_2)^2, \quad \Delta l_2 = L - L \cos \theta = L(1 - \cos \theta)$$

$$(V_e)_2 = \frac{1}{2} K [L(1 - \cos \theta)]^2 = \frac{1}{2} K L^2 (1 - \cos \theta)^2$$

$$(V_g)_2 = -W h_2 = -W \left(\frac{1}{2} L \sin \theta\right)$$

$$0 = \frac{1}{6} m L^2 \omega^2 + \frac{1}{2} K L^2 (1 - \cos \theta)^2 - \frac{1}{2} W L \sin \theta$$

$$\omega = \sqrt{\frac{6}{m L^2} \left[\frac{1}{2} W L \sin \theta - \frac{1}{2} K L^2 (1 - \cos \theta)^2 \right]}$$

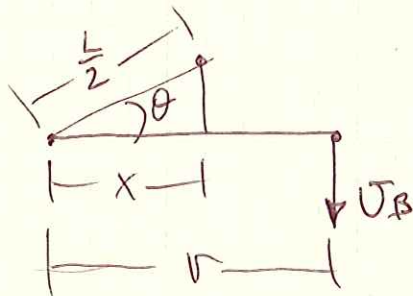
PROB. 17-38 CONT.

$$\omega = \sqrt{\frac{3g}{WL} \cdot [W \sin \theta - KL(1 - \cos \theta)^2]}$$

$$\omega = \sqrt{\frac{3(32.2 \frac{\text{ft}}{\text{s}^2})}{(9 \text{ LB}) \left(\frac{25}{12} \text{ ft}\right)} \cdot \left[(9 \text{ LB}) \sin 30^\circ - \left(36 \frac{\text{LB}}{\text{ft}}\right) \left(\frac{25}{12} \text{ ft}\right) (1 - \cos 30^\circ)^2 \right]}$$

$$\omega = 4.031 \frac{\text{RAD}}{\text{s}} \downarrow$$

$$v_B = v \omega$$



$$\cos \theta = \frac{x}{L/2}$$

$$x = \frac{1}{2} L \cos \theta$$

$$2x = L \cos \theta = v$$

$$v_B = L \cos \theta \cdot \omega$$

$$v_B = \left(\frac{25}{12} \text{ ft}\right) (\cos 30^\circ) \left(4.031 \frac{\text{RAD}}{\text{s}}\right) = 7.273 \frac{\text{ft}}{\text{s}} \downarrow$$