

A PLANAR MOTION OF RIGID BODIES WILL BE ANALYZED USING THE METHOD OF WORK AND ENERGY AND THE METHOD OF IMPULSE AND MOMENTUM.

WORK/ENERGY:

- WORK OF A FORCE
- WORK OF A COUPLE
- KINETIC ENERGY OF A RIGID BODY
- CONSERVATION OF ENERGY

IMPULSE/MOMENTUM:

- CONSERVATION OF ANGULAR MOMENTUM
- ECCENTRIC IMPACT OF RIGID BODIES

PRINCIPLE OF WORK AND ENERGY

$$T_1 + U_{1-2} = T_2$$

T_1 = INITIAL TOTAL KINETIC ENERGY OF RIGID BODY

T_2 = FINAL TOTAL K.E.

U_{1-2} = WORK OF ALL FORCES ON BODY

TOTAL K.E. : $T = \frac{1}{2} \sum_{i=1}^n \Delta m_i v_i^2$

n = NUMBER OF PARTICLES MAKING UP BODY

Δm_i = MASS OF PARTICLES

v_i = VELOCITY OF PARTICLES

$$U_{1-2} = \int \vec{F} \cdot d\vec{r} = \int_{s_1}^{s_2} (F \cos \alpha) ds$$

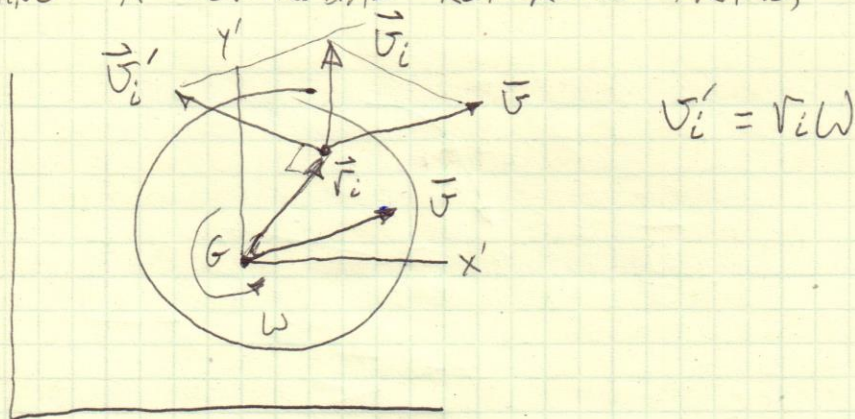
WORK OF A FORCE DURING DISPLACEMENT ALONG A PATH.

$$U_{1-2} = \int_{\theta_1}^{\theta_2} M d\theta$$

WORK OF A COUPLE DURING ~~AND~~ A FINITE ROTATION OF THE BODY. IF THE MOMENT M IS CONSTANT,

$$U_{1-2} = M (\theta_2 - \theta_1)$$

USING A CENTROIDAL REFERENCE FRAME, (SEC. 14.7):



$$T = \frac{1}{2} m \bar{U}^2 + \frac{1}{2} \sum_{i=1}^n \Delta m_i v_i'^2 = \frac{1}{2} m \bar{U}^2 + \frac{1}{2} \left(\sum_{i=1}^n r_i'^2 \Delta m_i \right) \omega^2$$

$$T = \frac{1}{2} M \bar{U}^2 + \frac{1}{2} \bar{I} \omega^2$$

TRANSL. ROTATION

\bar{I} = MASS MOMENT OF INERTIA ABOUT MASS CENTER G

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~~FOR SYSTEMS OF RIGID BODIES, THE PRINCIPLE OF WORK AND ENERGY IS~~

$$T_1 + U_{1-2} = T_2$$

~~T = KINETIC ENERGY OF ALL BODIES (TRANSL. + ROTATION)~~

~~U = WORK DONE BY FORCES ON BODIES~~

CONSERVATION OF ENERGY (NO FRICTION DISSIPATION)

FOR A SYSTEM OF RIGID BODIES:

$$T_1 + V_1 = T_2 + V_2 \quad (KE + PE = \text{CONSTANT})$$

POWER = TIME RATE AT WHICH WORK IS DONE

FOR A BODY ACTED ON BY A FORCE MOVING
WITH A VELOCITY \vec{v} ;

$$P = \vec{F} \cdot \vec{v} \quad (\text{N}) \left(\frac{\text{m}}{\text{s}} \right)$$

FOR A RIGID BODY ROTATING AT ANGULAR VELOCITY ω ,

$$P = M\omega \quad (\text{N} \cdot \text{m}) \left(\frac{\text{RAD}}{\text{s}} \right) = \frac{\text{N} \cdot \text{m}}{\text{s}}$$