

# Chapter 2: Numeric, Cell, and Structure Arrays

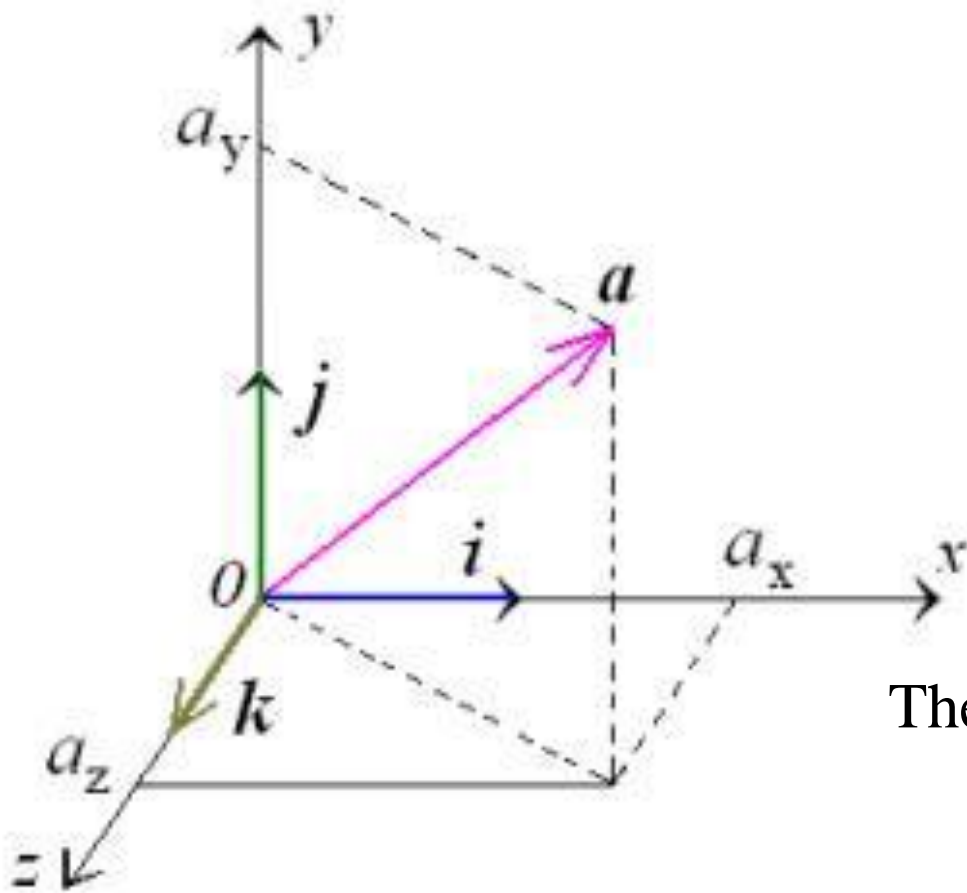
## Topics Covered:

- Vectors
  - Definition
  - Addition
  - Multiplication
    - Scalar, Dot, Cross
- Matrices
  - Row, Column, Square
  - Transpose
  - Addition
  - Multiplication
    - Scalar-Matrix, Matrix-Matrix
  - Element-by-Element Operations
    - Multiplication, Division, Exponentiation, Vectorized Functions
  - Array Addressing

# Vectors

A **Scalar** is a number that has magnitude but no direction (Temperature reading on a thermometer, pressure reading on a pressure gage)

A **Vector** has both magnitude and direction. Vectors are used by engineers to represent position, velocity, acceleration, force, torque, angular velocity, angular acceleration, linear momentum, angular momentum, heat flux, magnetic flux, etc.



The **Vector**  $\vec{a}$  is composed of three Cartesian **Components**:

$$\vec{a} = (a_x)\hat{i} + (a_y)\hat{j} + (a_z)\hat{k}$$

$\hat{i}$ ,  $\hat{j}$ , and  $\hat{k}$  are **Unit Vectors** in the  $x, y, z$  directions.

The **Length** of a **Unit Vector** is one.

The **Length** of the **Vector**  $\vec{a}$  is called its **Magnitude**:

$$|\vec{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2}$$

**Vectors** are represented in MATLAB as:

$$\vec{a} = [a_x, a_y, a_z] \text{ or } [a_x \ a_y \ a_z]$$

Open up a new MATLAB Script File:

```
Editor - C:\Users\scott\Desktop\chapter2.m
chapter2.m x
1 -   clc
2 -   clear
3 -   a = [3, 7, 15]
4 -   Number_of_Elements = length(a)
5 -   Magnitude_of_the_Vector = norm(a)
6 -   Add_the_Elements = sum(a)
7 -   Maximum_Element = max(a)
8
```

Command Window

```
a =
     3     7    15

Number_of_Elements =
     3

Magnitude_of_the_Vector =
    16.8226

Add_the_Elements =
    25

Maximum_Element =
    15
```

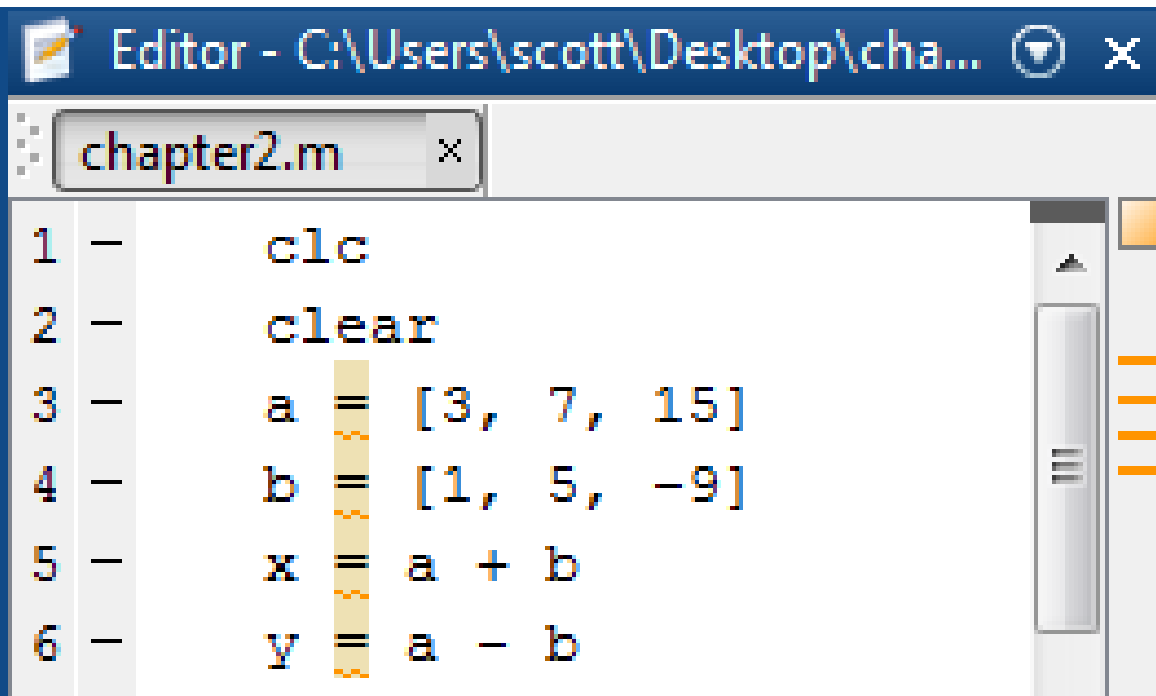
**Vector Addition:** Add the corresponding **Components** of the two **Vectors:**

$$\vec{a} + \vec{b} = [a_x, a_y, a_z] + [b_x, b_y, b_z]$$

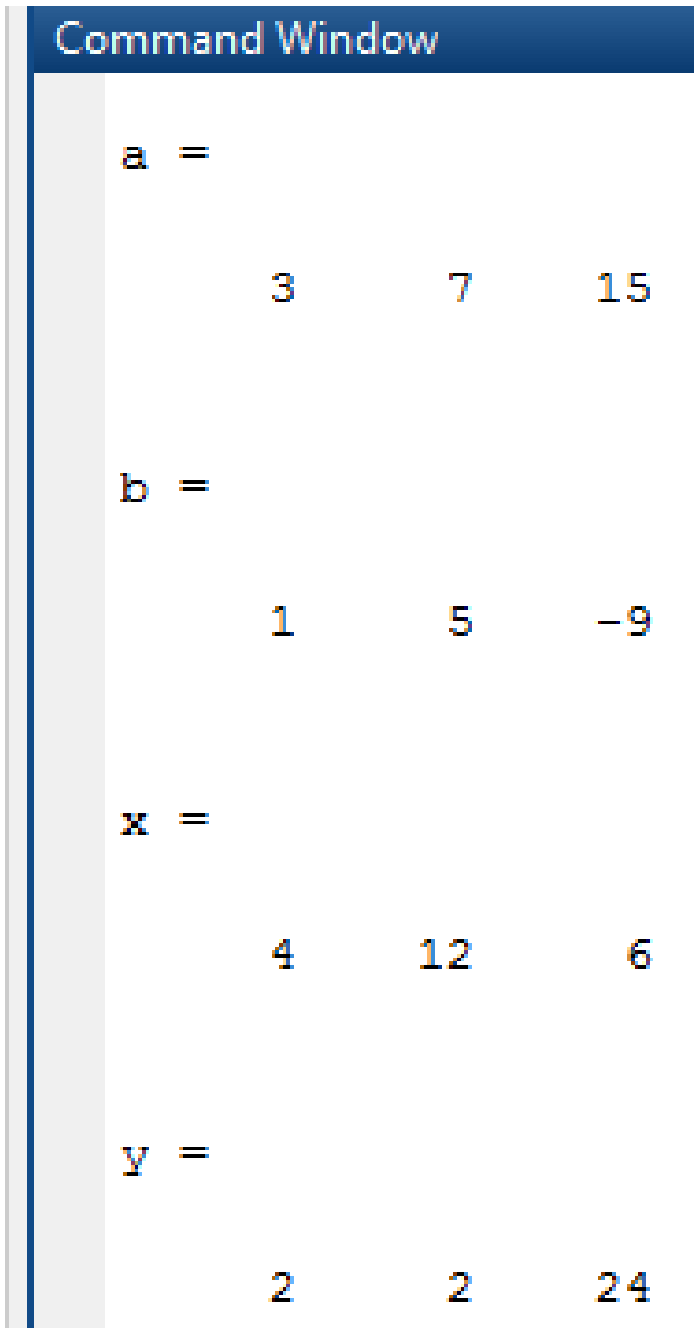
$$\vec{a} + \vec{b} = [(a_x + b_x), (a_y + b_y), (a_z + b_z)]$$

$$\vec{a} - \vec{b} = [(a_x - b_x), (a_y - b_y), (a_z - b_z)]$$

Modify and run the Script File as follows:



```
Editor - C:\Users\scott\Desktop\cha...  
chapter2.m  
1 - clc  
2 - clear  
3 - a = [3, 7, 15]  
4 - b = [1, 5, -9]  
5 - x = a + b  
6 - y = a - b
```



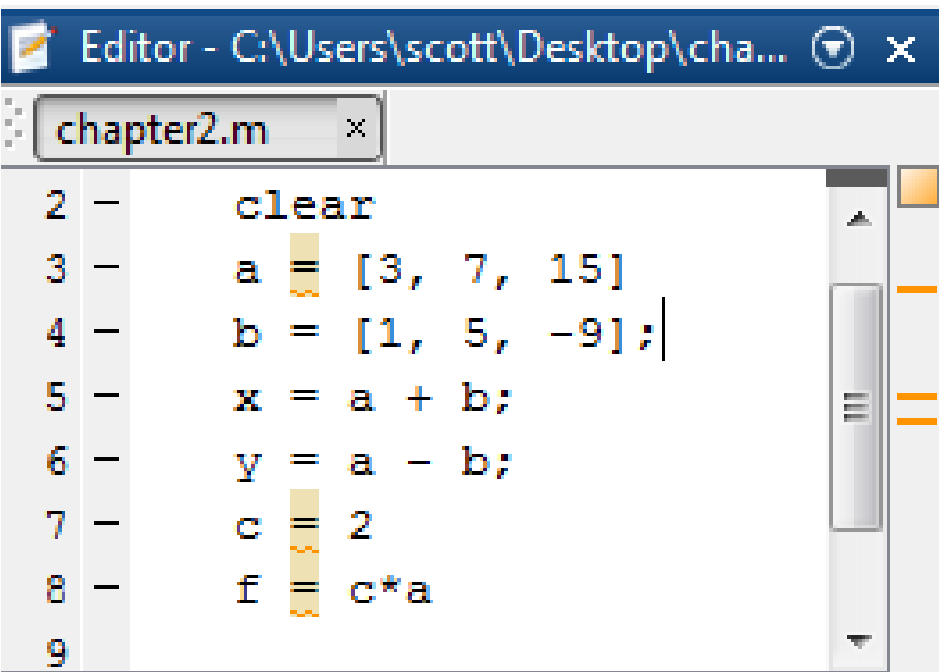
```
Command Window  
a =  
    3     7    15  
  
b =  
    1     5    -9  
  
x =  
    4    12     6  
  
y =  
    2     2    24
```

# Vector Multiplication

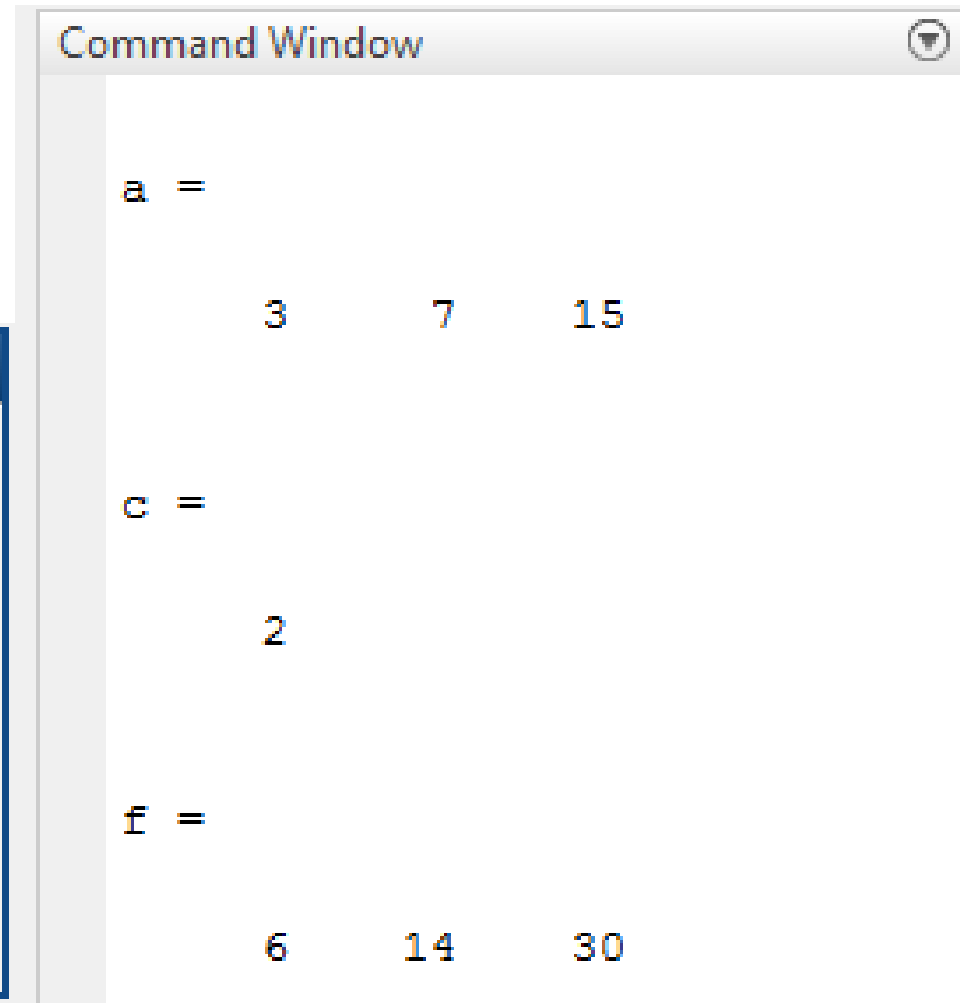
**Scalar × Vector:** Distribute the **Scalar** to each **Component** of the **Vector**:

$$c\vec{a} = [ca_x, ca_y, ca_z]$$

Modify and run the Script File as follows:



```
Editor - C:\Users\scott\Desktop\cha...  
chapter2.m  
2 - clear  
3 - a = [3, 7, 15]  
4 - b = [1, 5, -9];  
5 - x = a + b;  
6 - y = a - b;  
7 - c = 2  
8 - f = c*a  
9
```



```
Command Window  
a =  
    3    7   15  
  
c =  
    2  
  
f =  
    6   14   30
```

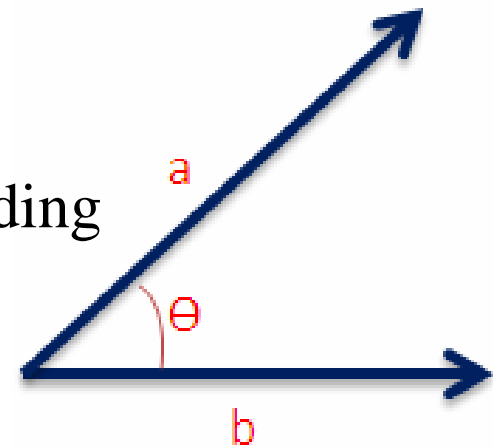
# Vector Dot Product

**Vector · Vector:** Sum of the products of the corresponding Components of the two Vectors.

$$\vec{a} \cdot \vec{b} = |\vec{a}| \times |\vec{b}| \times \cos \theta = \text{Scalar}$$

$$\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a} = a_x b_x + a_y b_y + a_z b_z$$

Modify and run the Script File as follows:



```
Editor - C:\Users\scott\Desktop\cha...
chapter2.m
3 - a = [3, 7, 15]
4 - b = [1, 5, -9]
5 - x = a + b;
6 - y = a - b;
7 - c = 2;
8 - f = c*a;
9 - g = dot(a,b)
10
```

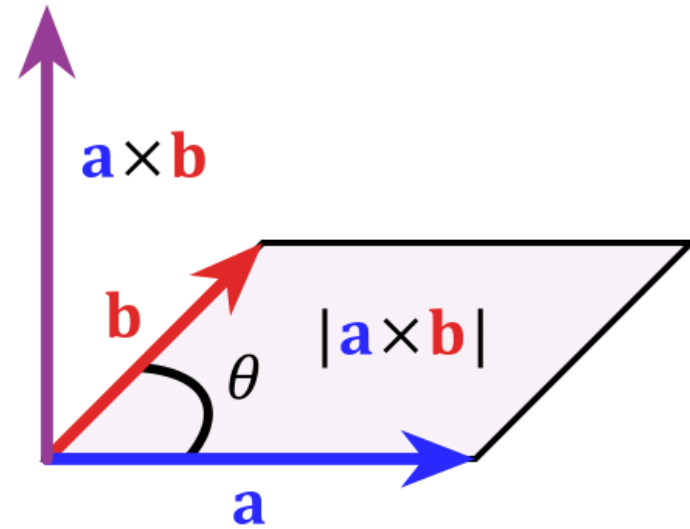
```
Command Window
a =
     3     7    15
b =
     1     5    -9
g =
    -97
```

# Vector Cross Product

**Vector  $\times$  Vector:** Results in a **Vector Normal** (Perpendicular) to the plane defined by the two vectors being crossed.

$$\vec{a} \times \vec{b} = (|\vec{a}||\vec{b}| \sin \theta) \hat{n} = \mathbf{Vector}$$

$\hat{n}$  is the **Unit Vector Normal** to the **Plane**.



$$\vec{a} \times \vec{b} = -(\vec{b} \times \vec{a}) = \begin{bmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{bmatrix} \quad \begin{array}{l} \text{Determinant} \\ \text{Method} \end{array}$$

$$\vec{a} \times \vec{b} = (a_y b_z - a_z b_y) \hat{i} - (a_x b_z - a_z b_x) \hat{j} + (a_x b_y - a_y b_x) \hat{k}$$



Modify and run the Script File as follows:

```
Editor - C:\Users\scott\Desktop\cha... x
chapter2.m x
1 -      clc
2 -      clear
3 -      a = [3, 7, 15]
4 -      b = [1, 5, -9]
5 -      x = a + b;
6 -      y = a - b;
7 -      c = 2;
8 -      f = c*a;
9 -      g = dot(a,b);
10 -     h = cross(a,b)
11 -     m = cross(b,a)
12
```

## Command Window

```
a =
     3     7    15

b =
     1     5    -9

h =
    -138     42     8

m =
    138    -42    -8
```

# Matrices

A **Matrix** is a rectangular **Array** of numbers arranged in **Rows** and **Columns**. The individual numbers in a **Matrix** are called **Elements**.

$$\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix}$$

← Row 1

↑ Column 1

$A_{\text{Row-Column}}$ :  $A_{23}$  = Number in the Second Row, Third Column

In MATLAB, use a **Comma** to separate **Columns**; use a **Semi-Colon** to separate **Rows**:

$$\mathbf{A} = [A_{11}, A_{12}, A_{13}; A_{21}, A_{22}, A_{23}; A_{31}, A_{32}, A_{33}]$$

Modify and run the Script File as follows:

```
Editor - C:\Users\scott\Desktop\chapter2.m*
chapter2.m* x
1 -      clc
2 -      clear
3 -      a = [3, 7, 15];
4 -      b = [1, 5, -9];
5 -      x = a + b;
6 -      y = a - b;
7 -      c = 2;
8 -      f = c*a;
9 -      g = dot(a,b);
10 -     h = cross(a,b);
11 -     m = cross(b,a);
12
13 -     A = [1, 2, 3; 4, 5, 6; 7, 8, 9]
14
```

```
Command Window
A =
     1     2     3
     4     5     6
     7     8     9
```

**Row Vector:** A **Matrix** with one **Row**, multiple **Columns**

$$\mathbf{B} = [B_{11}, B_{12}, B_{13}]$$

**Column Vector:** A **Matrix** with one **Column**, multiple **Rows**

$$\mathbf{C} = \begin{bmatrix} C_{11} \\ C_{21} \\ C_{31} \end{bmatrix}$$

In MATLAB, create a **Column Vector** by using **Semi-Colons** to separate **Rows**

$$\mathbf{C} = [C_{11}; C_{12}; C_{13}]$$

**Square Matrix:** Number of **Rows** = Number of **Columns**

$$\mathbf{D} = \begin{bmatrix} D_{11} & D_{12} \\ D_{21} & D_{22} \end{bmatrix}$$

A **Vector** can be **Transposed** by switching the **Rows** and **Columns**.

$$\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix} \quad \mathbf{A}^T = \begin{bmatrix} A_{11} & A_{21} & A_{31} \\ A_{12} & A_{22} & A_{32} \\ A_{13} & A_{23} & A_{33} \end{bmatrix}$$

Modify and run the Script File as follows:

```
Editor - C:\Users\scott\Desktop\chapter2.m
chapter2.m
10 - h = cross(a,b);
11 - m = cross(b,a);
12
13 - A = [1, 2, 3; 4, 5, 6; 7, 8, 9]
14 - E = A'
```

```
Command Window
A =
     1     2     3
     4     5     6
     7     8     9
E =
     1     4     7
     2     5     8
     3     6     9
```

**Matrix Addition:** The **Size** of the two **Matrices** must be the same:

$$(2 \times 2) + (2 \times 2) = (2 \times 2) \quad (\text{Two Rows} \times \text{Two Columns})$$

$$\mathbf{D} + \mathbf{F} = \begin{bmatrix} D_{11} & D_{12} \\ D_{21} & D_{22} \end{bmatrix} + \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix}$$

$$\mathbf{D} + \mathbf{F} = \begin{bmatrix} (D_{11} + F_{11}) & (D_{12} + F_{12}) \\ (D_{21} + F_{21}) & (D_{22} + F_{22}) \end{bmatrix}$$

Modify and run the Script File as follows:

```
Editor - C:\Users\scott\Desktop\chapter2.m
chapter2.m
13 - A = [1, 2, 3; 4, 5, 6; 7, 8, 9];
14 - E = A';
15
16 - D = [1 2; 3 4]
17 - F = [5 6; 7 8]
18 - G = D + F
19
```

```
Command Window
D =
     1     2
     3     4
F =
     5     6
     7     8
G =
     6     8
    10    12
```

# Scalar $\times$ Matrix Multiplication: The Scalar is Distributed to all of the Elements of the Matrix:

$$c\mathbf{A} = \begin{bmatrix} cA_{11} & cA_{12} & cA_{13} \\ cA_{21} & cA_{22} & cA_{23} \\ cA_{31} & cA_{32} & cA_{33} \end{bmatrix}$$

Modify and run the Script File as follows:

```
Editor - C:\Users\scott\Desktop\chapter2.m  
chapter2.m ×  
12  
13 - A = [1, 2, 3; 4, 5, 6; 7, 8, 9]  
14 - E = A';  
15  
16 - D = [1 2; 3 4];  
17 - F = [5 6; 7 8];  
18 - G = D + F;  
19 - c = 3  
20 - H = c*A  
21
```

```
Command Window  
A =  
  
     1     2     3  
     4     5     6  
     7     8     9  
  
c =  
  
     3  
  
H =  
  
     3     6     9  
    12    15    18  
    21    24    27
```

**Matrix × Matrix Multiplication: The Size of the two Matrices Can Be the Same:**  $(2 \times 2) \times (2 \times 2) = (2 \times 2)$

$$\mathbf{D} \times \mathbf{F} = \begin{bmatrix} D_{11} & D_{12} \\ D_{21} & D_{22} \end{bmatrix} \times \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix}$$

$$\mathbf{D} \times \mathbf{F} = \begin{bmatrix} (D_{11}F_{11} + D_{12}F_{21}) & (D_{11}F_{12} + D_{12}F_{22}) \\ (D_{21}F_{11} + D_{22}F_{21}) & (D_{21}F_{12} + D_{22}F_{22}) \end{bmatrix}$$

Modify and run the Script File as follows:

```
Editor - C:\Users\scott\Desktop\
chapter2.m*
15
16 - D = [1 2; 3 4]
17 - F = [5 6; 7 8]
18 - G = D + F;
19 - c = 3;
20 - H = c*A;
21 - J = D*F
```

### Command Window

D =

```
1 2
3 4
```

J =

```
19 22
43 50
```

F =

```
5 6
7 8
```



**Matrix × Matrix Multiplication: The Sizes of the two Matrices Can Be Different: The Inner Sizes Must be the Same; the Outer Sizes Can be Different.**

Inner Sizes

$$(3 \times 2) \times (2 \times 3) = (3 \times 3)$$

Outer Sizes

$$\mathbf{K} \times \mathbf{L} = \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \\ K_{31} & K_{32} \end{bmatrix} \times \begin{bmatrix} L_{11} & L_{12} & L_{13} \\ L_{21} & L_{22} & L_{23} \end{bmatrix}$$

$$= \begin{bmatrix} (K_{11}L_{11} + K_{12}L_{21}) & (K_{11}L_{12} + K_{12}L_{22}) & (K_{11}L_{13} + K_{12}L_{23}) \\ (K_{21}L_{11} + K_{22}L_{21}) & (K_{21}L_{12} + K_{22}L_{22}) & (K_{21}L_{13} + K_{22}L_{23}) \\ (K_{31}L_{11} + K_{32}L_{21}) & (K_{31}L_{12} + K_{32}L_{22}) & (K_{31}L_{13} + K_{32}L_{23}) \end{bmatrix}$$

Modify and run the Script File as follows:

```
Editor - C:\Users\scott\Desktop\chapter2.m
chapter2.m
20 - H = C*A;
21 - J = D*F;
22
23 - K = [1 2; 3 4; 5 6]
24 - L = [7 8 9; 10 11 12]
25 - M = K*L
```

```
Command Window
K =
     1     2
     3     4
     5     6

L =
     7     8     9
    10    11    12

M =
    27    30    33
    61    68    75
    95   106   117
```

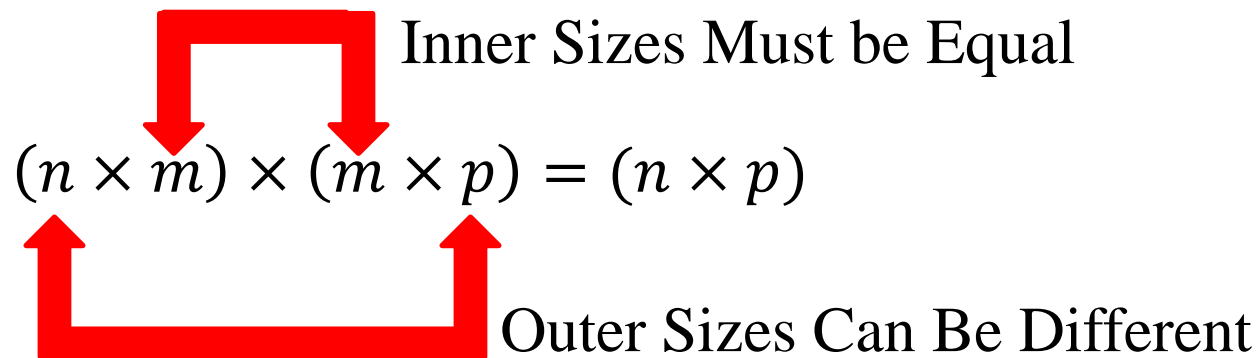
What Happens when you Reverse the Order of Multiplication? Try it!

$$(2 \times 3) \times (3 \times 2) = (2 \times 2)$$

$$\mathbf{L} \times \mathbf{K} = \begin{bmatrix} L_{11} & L_{12} & L_{13} \\ L_{21} & L_{22} & L_{23} \end{bmatrix} \times \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \\ K_{31} & K_{32} \end{bmatrix}$$

$$= \begin{bmatrix} (L_{11}K_{11} + L_{12}K_{21} + L_{13}K_{31}) & (L_{11}K_{12} + L_{12}K_{22} + L_{13}K_{32}) \\ (L_{21}K_{11} + L_{22}K_{21} + L_{23}K_{31}) & (L_{21}K_{12} + L_{22}K_{22} + L_{23}K_{32}) \end{bmatrix}$$

In General,


$$(n \times m) \times (m \times p) = (n \times p)$$

Inner Sizes Must be Equal

Outer Sizes Can Be Different

Another method to calculate the **Dot Product** of two vectors is to use **Matrix Multiplication**:

$$\mathbf{B} = [B_{11}, B_{12}, B_{13}]$$

$$\mathbf{C} = [C_{11}, C_{12}, C_{13}]$$

$$\mathbf{B} \cdot \mathbf{C} = [B_{11} \ B_{12} \ B_{13}] * \begin{bmatrix} C_{11} \\ C_{21} \\ C_{31} \end{bmatrix}$$

**Verify this using MATLAB!**

**Let:**

$$\mathbf{B} = [1, 2, 3]$$

$$\mathbf{C} = [4, 5, 6]$$

## Element × Element Multiplication:

Element-by-Element Multiplication is often used in engineering calculations. It is defined only for arrays that have the same size.

$$\mathbf{D} \times \mathbf{F} = \begin{bmatrix} D_{11} & D_{12} \\ D_{21} & D_{22} \end{bmatrix} .* \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix}$$

$$\mathbf{D} \times \mathbf{F} = \begin{bmatrix} (D_{11}F_{11}) & (D_{12}F_{12}) \\ (D_{21}F_{21}) & (D_{22}F_{22}) \end{bmatrix}$$

```

61      68
95     106

```

```
D =
```

```

1      2
3      4

```

```
F =
```

```

5      6
7      8

```

```
N =
```

```

5      12
21     32

```

```

Editor - C:\Users\scott\Desktop\cl
chapter2.m ×
37 - D = [1 2; 3 4]
38 - F = [5 6; 7 8]
39
40 - N = D.*F
41

```

## Element × Element Division:

Element-by-Element Division is also defined only for arrays that have the same size.

$$\mathbf{D} ./ \mathbf{F} = \begin{bmatrix} D_{11} & D_{12} \\ D_{21} & D_{22} \end{bmatrix} ./ \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix}$$

$$\mathbf{D} ./ \mathbf{F} = \begin{bmatrix} (D_{11}/F_{11}) & (D_{12}/F_{12}) \\ (D_{21}/F_{21}) & (D_{22}/F_{22}) \end{bmatrix}$$

```
Editor - C:\Users\scott\Desktop\c
chapter2.m
```

```
37 - D = [1 2; 3 4]
38 - F = [5 6; 7 8]
39 - N = D.*F;
40
41 - P = D./F
42
```

### Command Window

```
D =
     1     2
     3     4

F =
     5     6
     7     8

P =
    0.2000    0.3333
    0.4286    0.5000
```

## Element × Element Exponentiation:

Element-by-Element Exponentiation is also defined only for arrays that have the same size.

$$\mathbf{D} \cdot ^\wedge \mathbf{F} = \begin{bmatrix} D_{11} & D_{12} \\ D_{21} & D_{22} \end{bmatrix} \cdot ^\wedge \begin{bmatrix} F_{11} & F_{12} \\ F_{21} & F_{22} \end{bmatrix}$$

$$\mathbf{D} \cdot ^\wedge \mathbf{F} = \begin{bmatrix} (D_{11} \wedge F_{11}) & (D_{12} \wedge F_{12}) \\ (D_{21} \wedge F_{21}) & (D_{22} \wedge F_{22}) \end{bmatrix}$$

### Command Window

D =

```
1 2
3 4
```

F =

```
5 6
7 8
```

Q =

```
1 64
2187 65536
```

Editor - C:\Users\scott\Desktop

chapter2.m

```
37 - D = [1 2; 3 4]
```

```
38 - F = [5 6; 7 8]
```

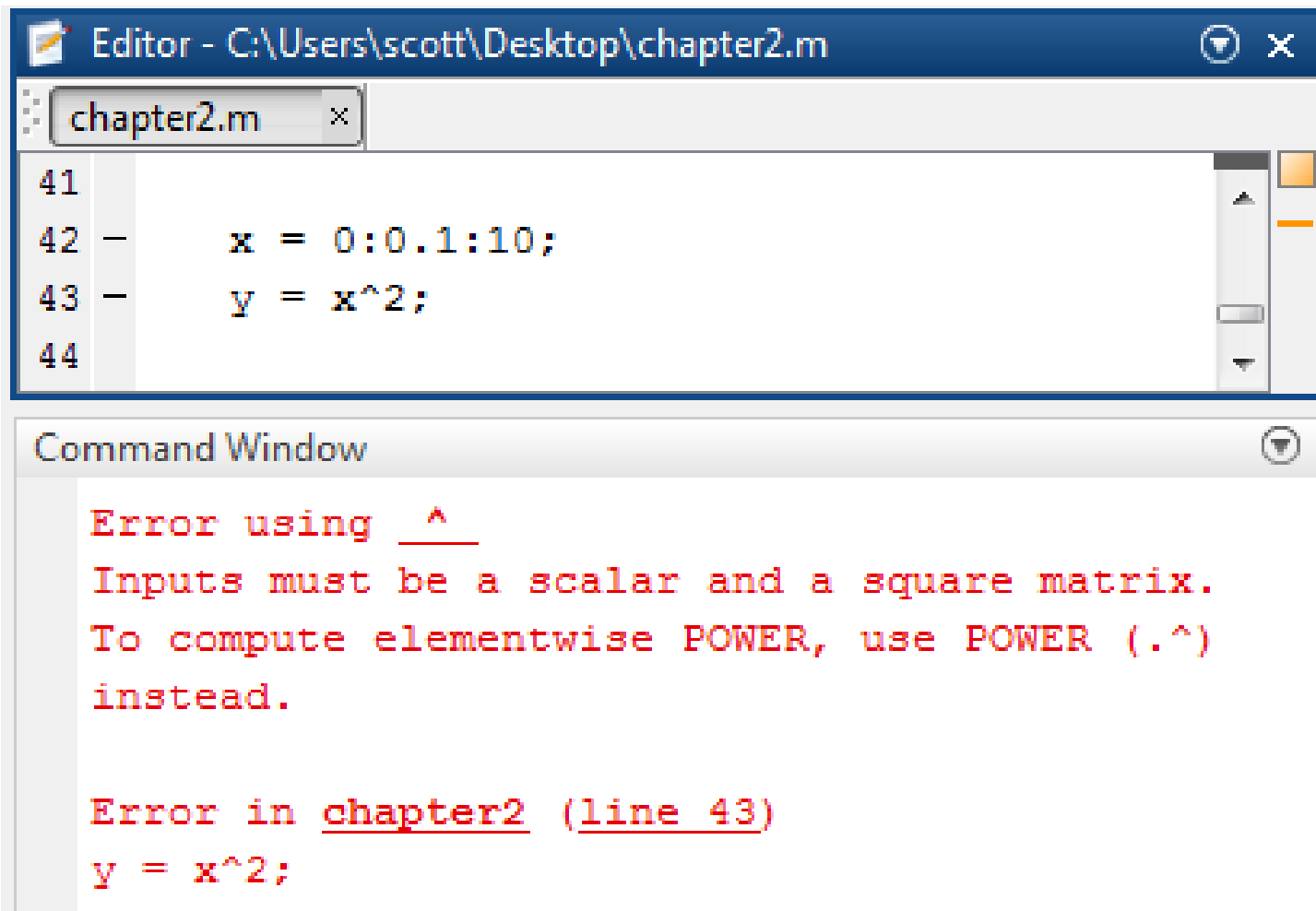
```
39 - N = D.*F;
```

```
40 - P = D./F;
```

```
41 - Q = D.^F
```

## Vectorized Functions:

When you use functions like  $\sin(x)$ ,  $\text{atan}(x)$  and  $\exp(x)$  on vectors, the results of the functions become vectors also. These are called **Vectorized Functions**. When multiplying or dividing these functions, you must use **Element-by-Element Operations**.



The image shows a MATLAB Editor window titled "Editor - C:\Users\scott\Desktop\chapter2.m" with a tab for "chapter2.m". The code in the editor is:

```
41  
42 -     x = 0:0.1:10;  
43 -     y = x^2;  
44
```

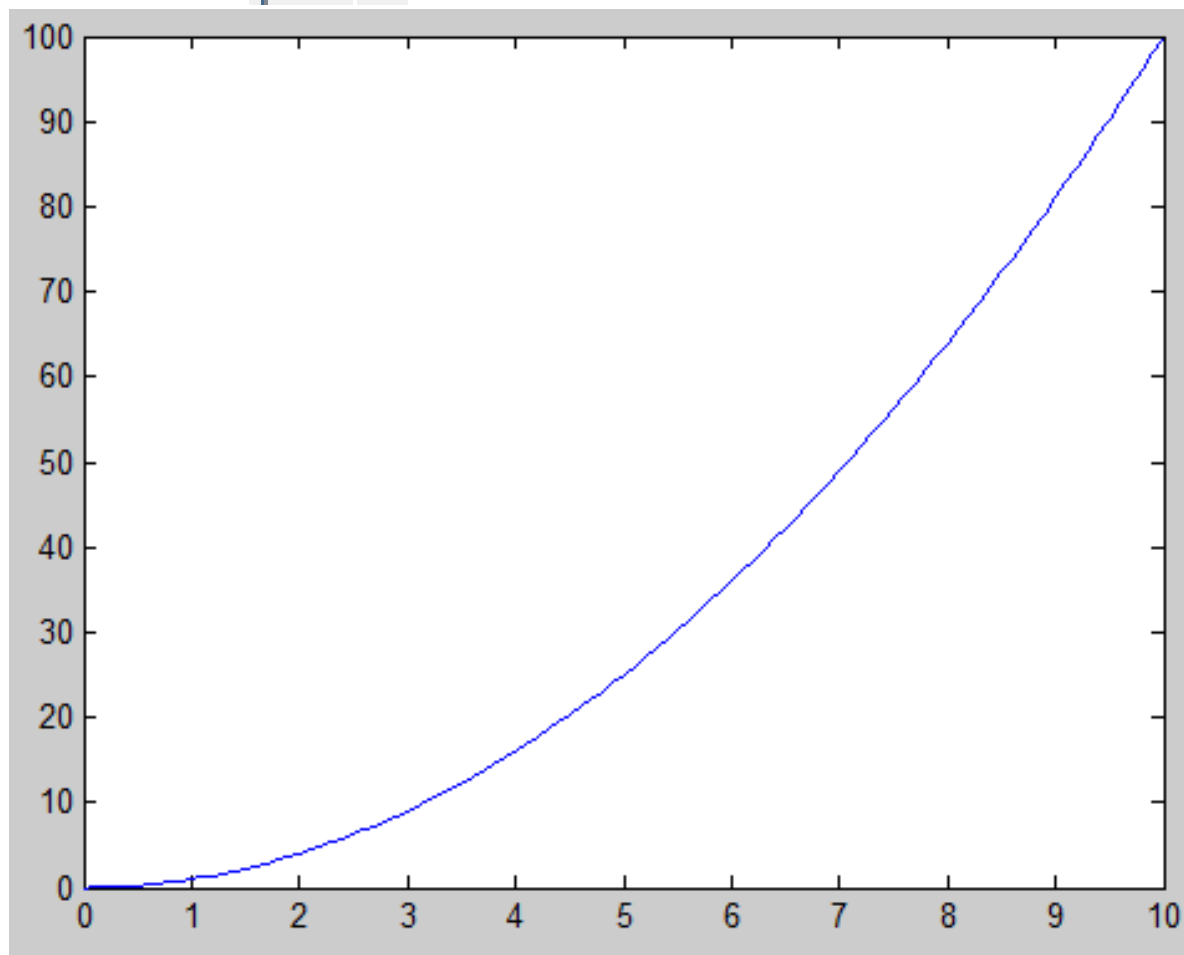
Below the editor is the Command Window, which displays the following error message:

```
Error using ^  
Inputs must be a scalar and a square matrix.  
To compute elementwise POWER, use POWER (.^)  
instead.  
  
Error in chapter2 (line 43)  
y = x^2;
```

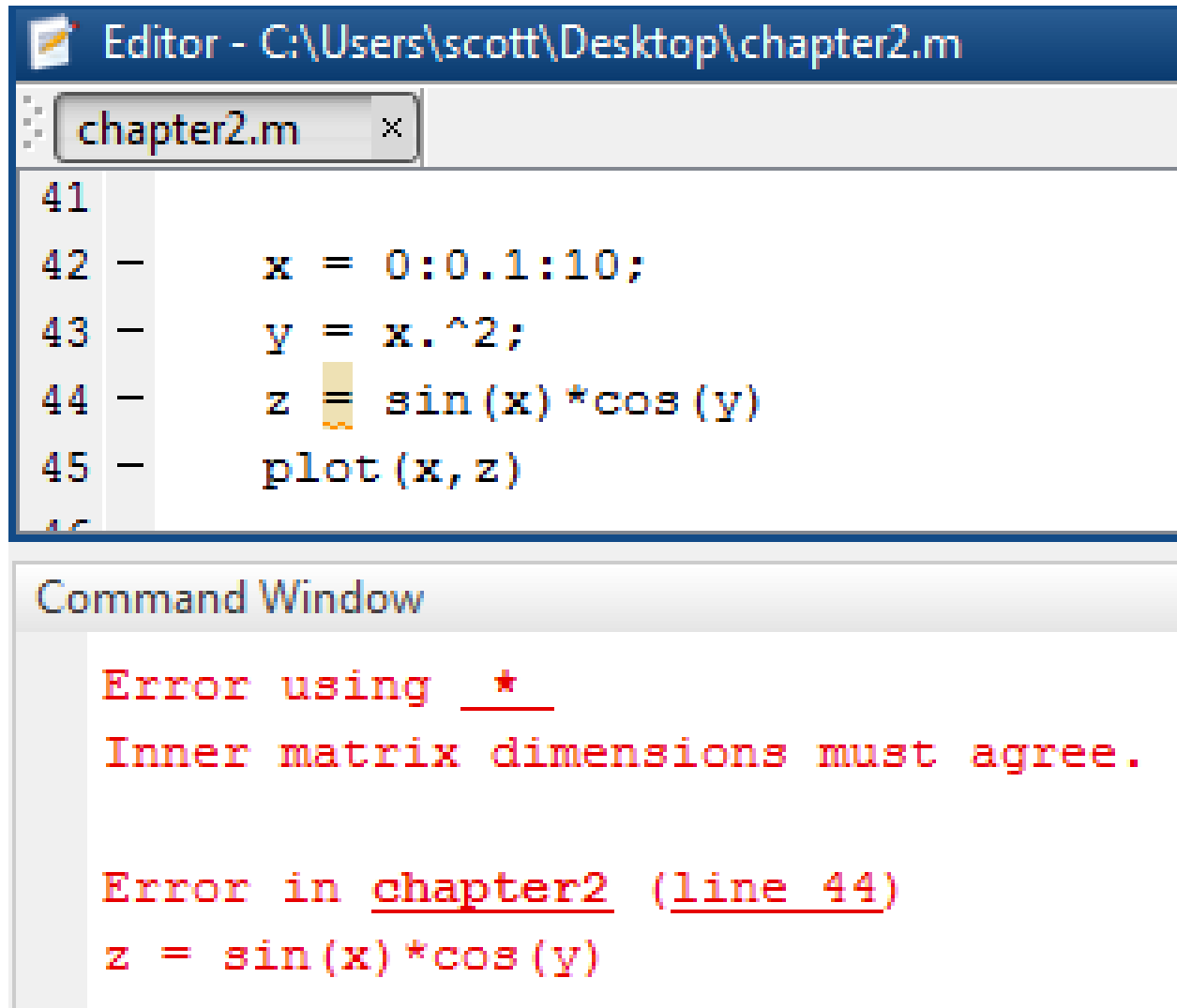


# Vectorized Functions:

```
Editor - C:\Users\scott\Desktop  
chapter2.m ×  
42 - x = 0:0.1:10;  
43 - y = x.^2;  
44 - plot(x, y)
```



## Vectorized Functions:



The image shows a MATLAB Editor window titled "Editor - C:\Users\scott\Desktop\chapter2.m" with a single tab for "chapter2.m". The code in the editor is as follows:

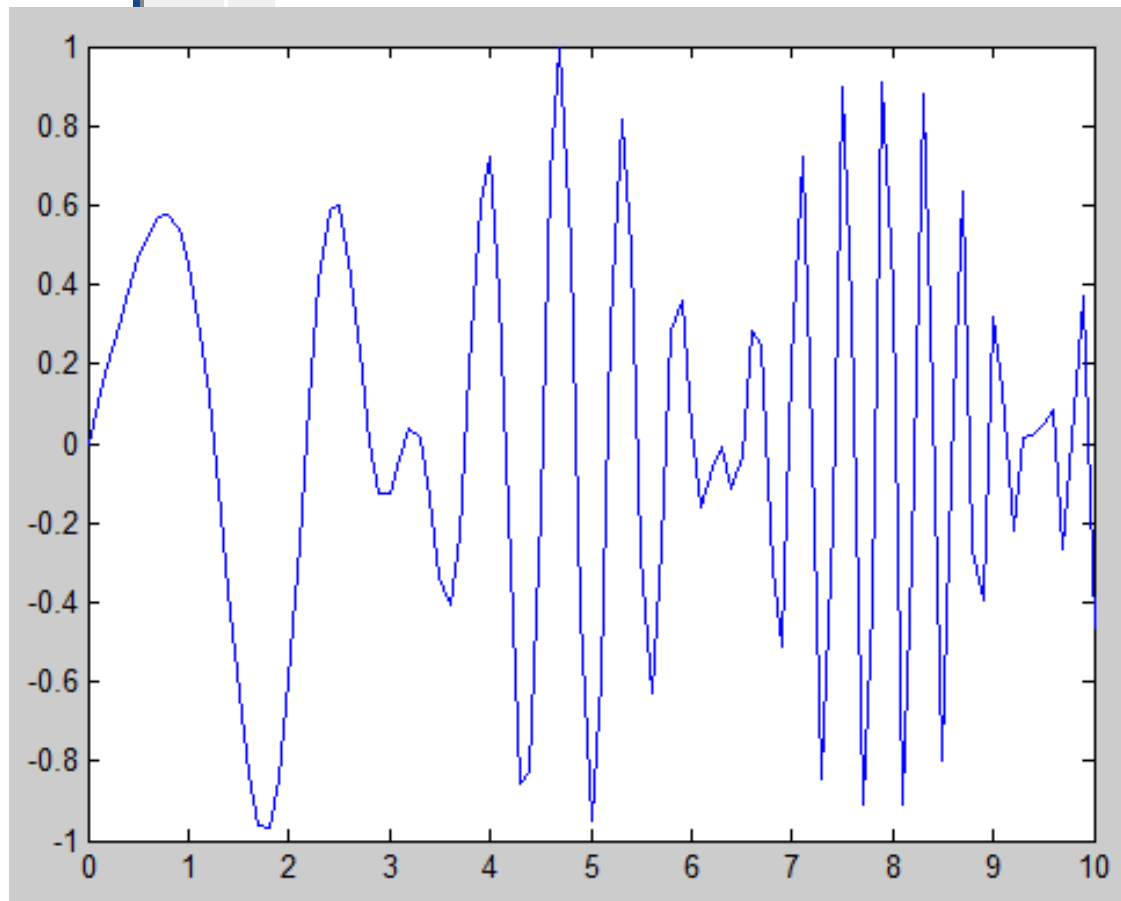
```
41  
42 -     x = 0:0.1:10;  
43 -     y = x.^2;  
44 -     z = sin(x)*cos(y)  
45 -     plot(x,z)
```

Below the editor is the Command Window, which displays the following error message in red text:

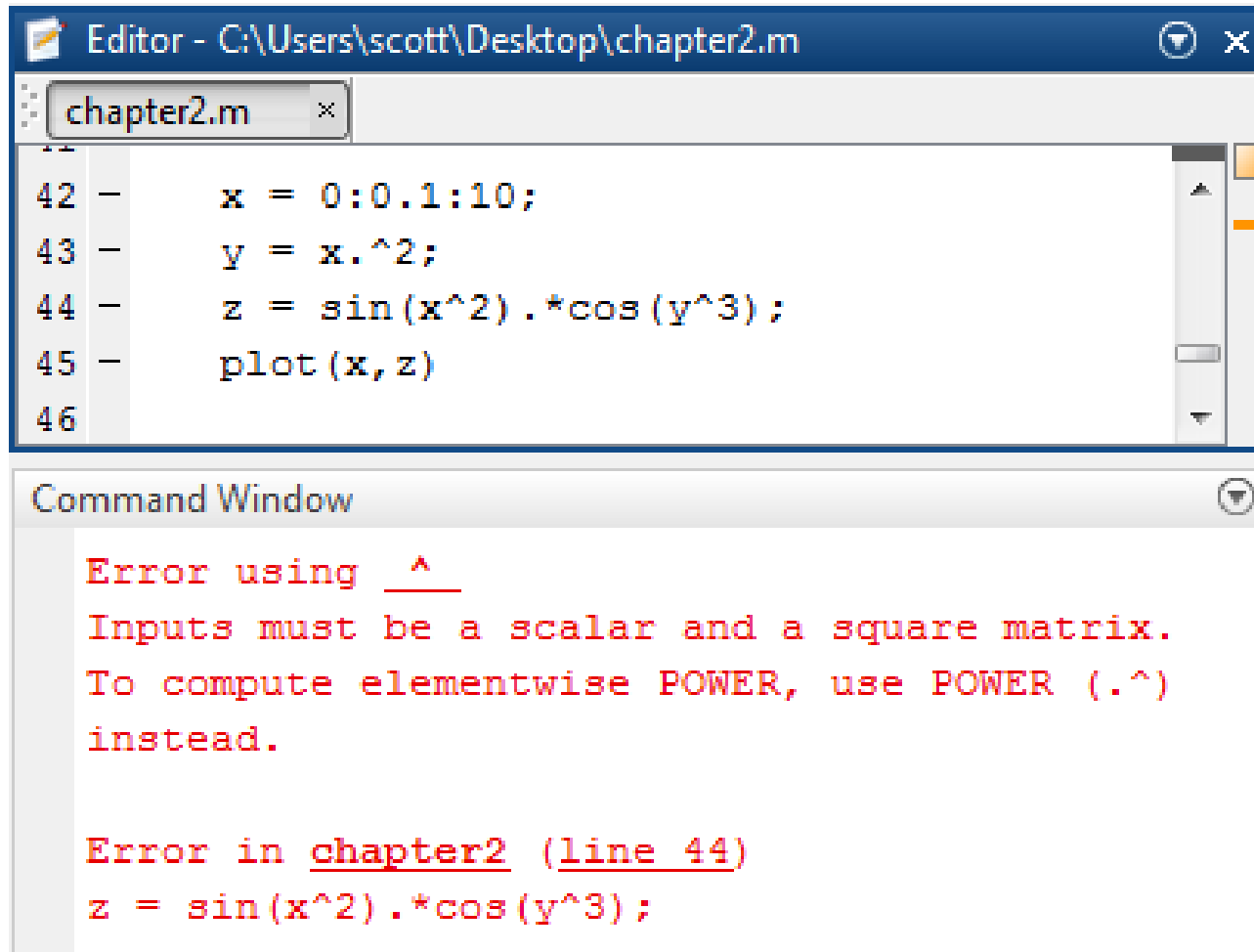
```
Error using *  
Inner matrix dimensions must agree.  
  
Error in chapter2 (line 44)  
z = sin(x)*cos(y)
```

# Vectorized Functions:

```
Editor - C:\Users\scott\Desktop\chapter2
chapter2.m x
42 - x = 0:0.1:10;
43 - y = x.^2;
44 - z = sin(x) .* cos(y);
45 - plot(x,z)
```



# Vectorized Functions:



The image shows a MATLAB Editor window titled "Editor - C:\Users\scott\Desktop\chapter2.m" with a tab for "chapter2.m". The code in the editor is as follows:

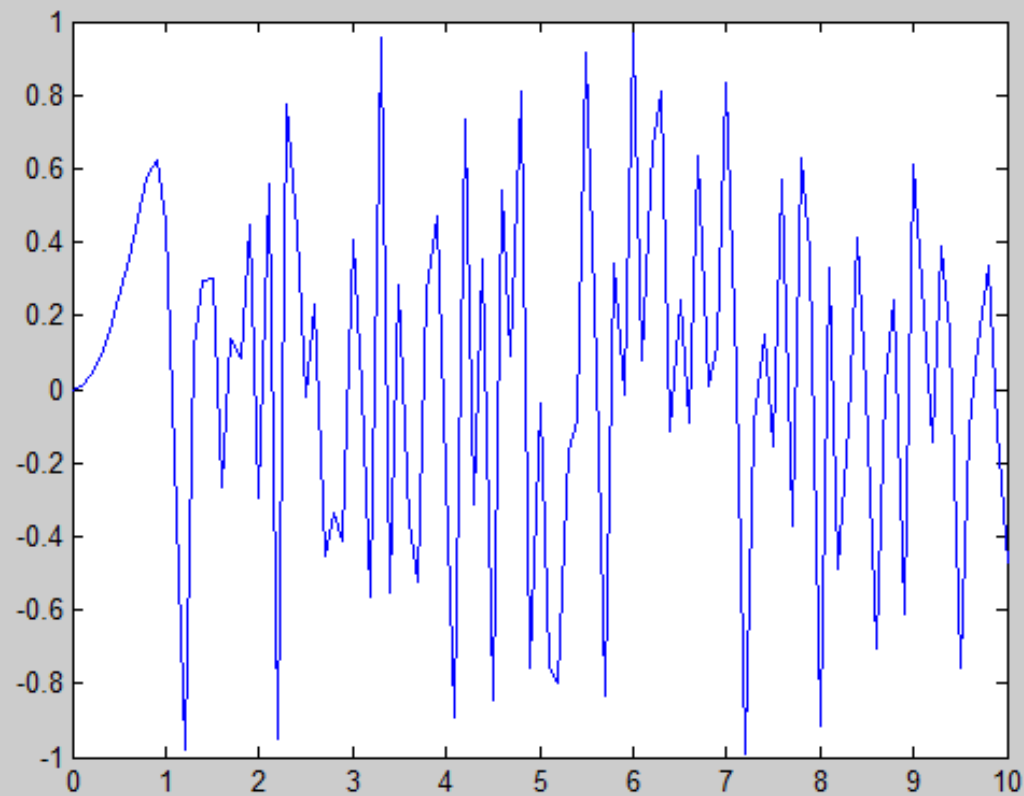
```
42 -     x = 0:0.1:10;  
43 -     y = x.^2;  
44 -     z = sin(x^2).*cos(y^3);  
45 -     plot(x,z)  
46
```

Below the editor is the Command Window, which displays the following error message:

```
Error using ^  
Inputs must be a scalar and a square matrix.  
To compute elementwise POWER, use POWER (.^)  
instead.  
  
Error in chapter2 (line 44)  
z = sin(x^2).*cos(y^3);
```

# Vectorized Functions:

```
Editor - C:\Users\scott\Desktop\chapter2.m  
chapter2.m ×  
42 - x = 0:0.1:10;  
43 - y = x.^2;  
44 - z = sin(x.^2).*cos(y.^3);  
45 - plot(x,z)
```



# Array Addressing

Now that you know how to create arrays, you need to be able to use specific elements, or rows, or columns in calculations. This is called **Array Addressing**. The **Colon** operator allows us to select individual elements, rows, columns, or parts of arrays.

Editor - C:\Users\scott\Desktop\chapter2.m

chapter2.m

```

23 -      K = [1 2; 3 4; 5 6];
24 -      L = [7 8 9; 10 11 12];
25 -      M = K*L
26
27 -      a = M(2,3)
28 -      b = M(:,3)
29 -      c = M(3,:)
30 -      d = M(2:3,1:2)

```

```

M =

    27    30    33
    61    68    75
    95   106   117

```

```

a =

    75

```

```

b =

    33
    75
   117

```

```

c =

    95   106   117

```

```

d =

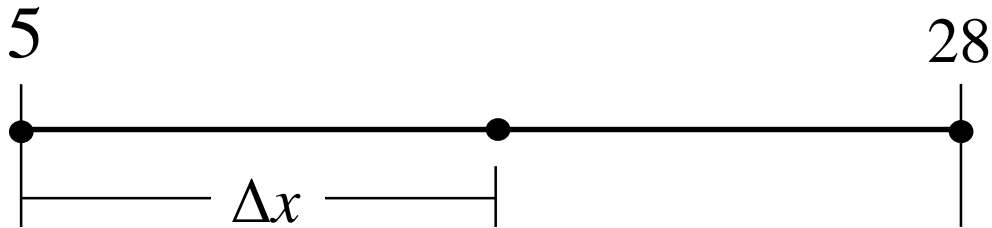
    61    68
    95   106

```

## Problem 2.1:

- Use two methods to create the vector  $x$  having 100 regularly spaced values starting at 5 and ending at 28.
- Use two methods to create the vector  $x$  having a regular spacing of 0.2 starting at 2 and ending at 14.

Start by looking at a simpler scenario, where three regularly spaced values are desired ( $n = 3$ ):



$$\Delta x = \frac{(28 - 5)}{(3 - 1)} = 11.5$$

$$5 + 11.5 = 16.5$$

$$16.5 + 11.5 = 28$$

In General,

$$\Delta x = \frac{(x_{\max} - x_{\min})}{(n - 1)}$$

Editor - C:\Users\scott\Desktop\Problem2\_1.m

chapter2.m

Problem2\_1.m

```
1 -   clc
2 -   clear
3 -   xmin = 5
4 -   xmax = 28
5 -   N = 3
6 -   deltax = (xmax - xmin) / (N-1)
7 -   x = 5:deltax:28
```

```
xmin =
```

```
5
```

```
xmax =
```

```
28
```

```
N =
```

```
3
```

```
deltax =
```

```
11.5000
```

```
x =
```

```
5.0000
```

```
16.5000
```

```
28.0000
```



```
Editor - C:\Users\scott\Desktop\Problem2_1.m
chapter2.m × Problem2_1.m ×
1 -   clc
2 -   clear
3 -   xmin = 5
4 -   xmax = 28
5 -   N = 3
6 -   deltax = (xmax - xmin) / (N-1)
7 -   x = 5:deltax:28
8 -   x2 = linspace(5,28,N)
```

```
Command Window
xmin =
    5
xmax =
    28
N =
    3
deltax =
    11.5000
x =
    5.0000    16.5000    28.0000
x2 =
    5.0000    16.5000    28.0000
```

## **Problem 2.1:**

- a. Use two methods to create the vector  $x$  having 100 regularly spaced values starting at 5 and ending at 28.
- b. Use two methods to create the vector  $x$  having a regular spacing of 0.2 starting at 2 and ending at 14.

6. Type this matrix in MATLAB and use MATLAB to carry out the following instructions.

$$\mathbf{A} = \begin{bmatrix} 3 & 7 & -4 & 12 \\ -5 & 9 & 10 & 2 \\ 6 & 13 & 8 & 11 \\ 15 & 5 & 4 & 1 \end{bmatrix}$$

- Create a  $4 \times 3$  array  $\mathbf{B}$  consisting of all elements in the second through fourth columns of  $\mathbf{A}$ .
- Create a  $3 \times 4$  array  $\mathbf{C}$  consisting of all elements in the second through fourth rows of  $\mathbf{A}$ .
- Create a  $2 \times 3$  array  $\mathbf{D}$  consisting of all elements in the first two rows and the last three columns of  $\mathbf{A}$ .

8. Given the matrix

$$\mathbf{A} = \begin{bmatrix} 3 & 7 & -4 & 12 \\ -5 & 9 & 10 & 2 \\ 6 & 13 & 8 & 11 \\ 15 & 5 & 4 & 1 \end{bmatrix}$$

- a.* Find the maximum and minimum values in each column.
- b.* Find the maximum and minimum values in each row.

**13.\*** Given the matrices

$$\mathbf{A} = \begin{bmatrix} 56 & 32 \\ 24 & -16 \end{bmatrix} \quad \mathbf{B} = \begin{bmatrix} 14 & -4 \\ 6 & -2 \end{bmatrix}$$

Use MATLAB to

- a.* Find the result of **A** times **B** using the array product.
- b.* Find the result of **A** divided by **B** using array right division.
- c.* Find **B** raised to the third power element by element.

34. The volume of a parallelepiped can be computed from  $|\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C})|$ , where  $\mathbf{A}$ ,  $\mathbf{B}$ , and  $\mathbf{C}$  define three sides of the parallelepiped (see Figure P34). Compute the volume of a parallelepiped defined by  $\mathbf{A} = 5\mathbf{i}$ ,  $\mathbf{B} = 2\mathbf{i} + 4\mathbf{j}$ , and  $\mathbf{C} = 3\mathbf{i} - 2\mathbf{k}$ .

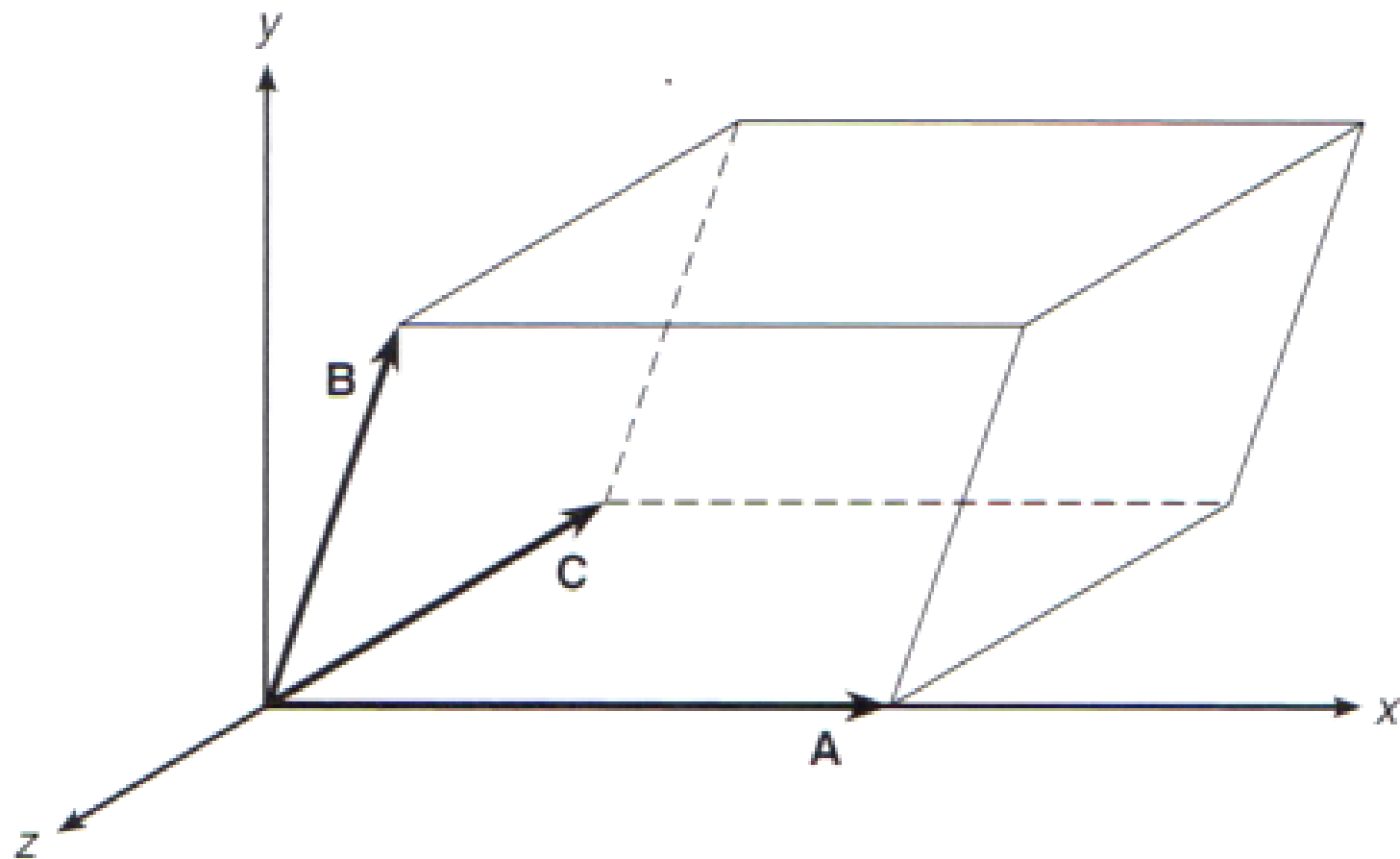


Figure P34