

Problem 9.28:

- 28.** The equation describing the water height h in a spherical tank with a drain at the bottom is

$$\pi(2rh - h^2) \frac{dh}{dt} = -C_d A \sqrt{2gh}$$

Suppose the tank's radius is $r = 3$ m and the circular drain hole has a radius of 2 cm. Assume that $C_d = 0.5$ and that the initial water height is $h(0) = 5$ m. Use $g = 9.81$ m/s².

- a. Use an approximation to estimate how long it takes for the tank to empty.
- b. Plot the water height as a function of time until $h(t) = 0$.

Use the Predictor-Corrector Method to solve this problem.

Problem setup:

Use the Predictor-Corrector method to solve this problem. Solve the differential equation for dh/dt :

$$\frac{dh}{dt} = \frac{-C_d A \sqrt{2gh}}{\pi(2rh - h^2)} = g(t, h)$$

Approximate the derivative as follows:

$$\frac{dh}{dt} \approx \frac{(h(t + \Delta t) - h(t))}{\Delta t} = g(t, h)$$

where Δt is the time step size. Solve for $h(t + \Delta t)$:

$$h(t + \Delta t) = h(t) + g(t, h)\Delta t$$

Put this equation into a form appropriate for computer solution. This is called the Difference Equation:

$$h(t_{k+1}) = h(t_k) + g[t_k, h(t_k)]\Delta t; \text{ where } t_{k+1} = t_k + \Delta t$$

Rewrite this equation as follows. This is the Euler Predictor Difference Equation:

$$x_{k+1} = h_k + g(t_k, h_k)\Delta t$$

This represents a preliminary estimate for h_{k+1} , which is designated as x_{k+1} to avoid confusion. This estimate is then corrected using the Trapezoidal Corrector Difference Equation:

$$h_{k+1} = h_k + \frac{\Delta t}{2} [g(t_k, h_k) + g(t_{k+1}, x_{k+1})]$$

Substitute the expression for $g(t, h)$ into the difference equations:

$$g(t, h) = \frac{-C_d A \sqrt{2gh}}{\pi(2rh - h^2)}$$

$$g(t_k, h_k) = \frac{-C_d A \sqrt{2gh_k}}{\pi(2rh_k - h_k^2)}$$

$$g(t_{k+1}, x_{k+1}) = \frac{-C_d A \sqrt{2gx_{k+1}}}{\pi(2rx_{k+1} - x_{k+1}^2)}$$

Predictor:

$$x_{k+1} = h_k + g(t_k, h_k)\Delta t$$

Corrector:

$$h_{k+1} = h_k + \frac{\Delta t}{2} [g(t_k, h_k) + g(t_{k+1}, x_{k+1})]$$

In the problem statement, the initial condition is $h(0) = 5.0$ m, $r_{\text{TANK}} = 3.0$ m, $r_{\text{DRAIN}} = 2.0$ cm = 0.02 m. Let $\Delta t = 100.0$. The order in which calculations are made is important, as shown below.

For $k = 1$:

$$h_1 = 5.0$$

$$t_1 = 0.0$$

$$A = \pi r_{\text{DRAIN}}^2 = \pi(0.02)^2 = 1.2566 \times 10^{-3}$$

$$g(t_1, h_1) = \frac{-C_d A \sqrt{2gh_1}}{\pi(2rh_1 - h_1^2)} = \frac{-(0.5)(1.2566 \times 10^{-3})\sqrt{2(9.81)(5.0)}}{\pi[2(3.0)(5.0) - (5.0)^2]} = -3.9617 \times 10^{-4}$$

Predictor:

$$x_2 = h_1 + g(t_1, h_1)\Delta t = (5.0) + (-3.9617 \times 10^{-4})(100.0) = 4.9604$$

Corrector:

$$t_2 = t_1 + \Delta t = 0.0 + 100.0 = 100.0$$

$$g(t_2, x_2) = \frac{-C_d A \sqrt{2gx_2}}{\pi(2rx_2 - x_2^2)} = \frac{-(0.5)(1.2566 \times 10^{-3})\sqrt{2(9.81)(4.9604)}}{\pi[2(3.0)(4.9604) - (4.9604)^2]} = -3.8260 \times 10^{-4}$$

$$h_2 = h_1 + \frac{\Delta t}{2} [g(t_1, h_1) + g(t_2, x_2)] = (5.0) + \frac{(100.0)}{2} [(-3.9617 \times 10^{-4}) + (-3.8260 \times 10^{-4})] = 4.9611$$

For $k = 2$:

$$g(t_2, h_2) = \frac{-C_d A \sqrt{2gh_2}}{\pi(2rh_2 - h_2^2)} = \frac{-(0.5)(1.2566 \times 10^{-3})\sqrt{2(9.81)(4.9611)}}{\pi[2(3.0)(4.9611) - (4.9611)^2]} = -3.8283 \times 10^{-4}$$

Predictor:

$$x_3 = h_2 + g(t_2, h_2)\Delta t = (4.9611) + (-3.8283 \times 10^{-4})(100.0) = 4.9228$$

Corrector:

$$t_3 = t_2 + \Delta t = 100.0 + 100.0 = 200.0$$

$$g(t_3, x_3) = \frac{-C_d A \sqrt{2gx_3}}{\pi(2rx_3 - x_3^2)} = \frac{-(0.5)(1.2566 \times 10^{-3})\sqrt{2(9.81)(4.9228)}}{\pi[2(3.0)(4.9228) - (4.9228)^2]} = -3.7065 \times 10^{-4}$$

$$\begin{aligned} h_3 &= h_2 + \frac{\Delta t}{2}[g(t_2, h_2) + g(t_3, x_3)] = (4.9611) + \frac{100.0}{2}[(-3.8283 \times 10^{-4}) + (-3.7065 \times 10^{-4})] \\ &= 4.9234 \end{aligned}$$

For $k = 3$:

$$g(t_3, h_3) = \frac{-C_d A \sqrt{2gh_3}}{\pi(2rh_3 - h_3^2)} = \frac{-(0.5)(1.2566 \times 10^{-3})\sqrt{2(9.81)(4.9234)}}{\pi[2(3.0)(4.9234) - (4.9234)^2]} = -3.7083 \times 10^{-4}$$

Predictor:

$$x_4 = h_3 + g(t_3, h_3)\Delta t = (4.9234) + (-3.7083 \times 10^{-4})(100.0) = 4.8863$$

Corrector:

$$t_4 = t_3 + \Delta t = 200.0 + 100.0 = 300.0$$

$$g(t_4, x_4) = \frac{-C_d A \sqrt{2gx_4}}{\pi(2rx_4 - x_4^2)} = \frac{-(0.5)(1.2566 \times 10^{-3})\sqrt{2(9.81)(4.8863)}}{\pi[2(3.0)(4.8863) - (4.8863)^2]} = -3.5984 \times 10^{-4}$$

$$\begin{aligned} h_4 &= h_3 + \frac{\Delta t}{2}[g(t_3, h_3) + g(t_4, x_4)] = (4.9234) + \frac{100.0}{2}[(-3.7083 \times 10^{-4}) + (-3.5984 \times 10^{-4})] \\ &= 4.8869 \end{aligned}$$

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1 % Problem 9.28
2 - clear
3 - clc
4 - disp('Problem 9.28: Scott Thomas')
5
6 - r = 3.0;% m
7 - rdrain = 0.02; % m
8 - g = 9.81; %m/s^2
9 - Cd = 0.5;
10 - A = pi*rdrain^2;
11
12 - N1 = 10;
13 - delta_t1 = 100.0;
14 - h1 = zeros(1,N1);
15 - t1 = zeros(1,N1);
16 - h1(1) = 5.0;
17 - for k = 1:N1
18 -     g1(k) = -Cd*A*sqrt(2*g*h1(k)) / (pi*(2*r*h1(k) - h1(k)^2));
19 -     % disp('Predictor')
20 -     x1(k+1) = h1(k) + g1(k)*delta_t1;
21 -     t1(k+1) = t1(k) + delta_t1;
22 -     g1(k+1) = -Cd*A*sqrt(2*g*x1(k+1)) / (pi*(2*r*x1(k+1) - x1(k+1)^2));
23 -     % disp('Corrector')
24 -     h1(k+1) = h1(k) + delta_t1/2*(g1(k) + g1(k+1));
25 -     % disp('End of Process')
26 - end
27 - x1
28 - h1
29

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x1 =

0	4.9604	4.9228	4.8863	4.8509	4.8163	4.7827	4.7498	4.7177	4.6862	4.6554
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h1 =

5.0000	4.9611	4.9234	4.8869	4.8514	4.8168	4.7831	4.7502	4.7180	4.6865	4.6557
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f1 >> |

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1 % Problem 9.28
2 - clear
3 - clc
4 - disp('Problem 9.28: Scott Thomas')
5
6 - r = 3.0;% m
7 - rdrain = 0.02; % m
8 - g = 9.81; %m/s^2
9 - Cd = 0.5;
10 - A = pi*rdrain^2;
11
12 - N1 = 252;
13 - delta_t1 = 100.0;
14 - h1 = zeros(1,N1);
15 - t1 = zeros(1,N1);
16 - h1(1) = 5.0;
17 - for k = 1:N1
18 -     g1(k) = -Cd*A*sqrt(2*g*h1(k))/(pi*(2*r*h1(k) - h1(k)^2));
19 -     % disp('Predictor')
20 -     x1(k+1) = h1(k) + g1(k)*delta_t1;
21 -     t1(k+1) = t1(k) + delta_t1;
22 -     g1(k+1) = -Cd*A*sqrt(2*g*x1(k+1))/(pi*(2*r*x1(k+1) - x1(k+1)^2));
23 -     % disp('Corrector')
24 -     h1(k+1) = h1(k) + delta_t1/2*(g1(k) + g1(k+1));
25 -     % disp('End of Process')
26 - end
27
28 - N2 = 25;
29 - delta_t2 = 1000.0;
30 - h2 = zeros(1,N2);
31 - t2 = zeros(1,N2);
32 - h2(1) = 5.0;
33 - for k = 1:N2
34 -     g2(k) = -Cd*A*sqrt(2*g*h2(k))/(pi*(2*r*h2(k) - h2(k)^2));
35 -     % disp('Predictor')
36 -     x2(k+1) = h2(k) + g2(k)*delta_t2;
37 -     t2(k+1) = t2(k) + delta_t2;
38 -     g2(k+1) = -Cd*A*sqrt(2*g*x2(k+1))/(pi*(2*r*x2(k+1) - x2(k+1)^2));
39 -     % disp('Corrector')
40 -     h2(k+1) = h2(k) + delta_t2/2*(g2(k) + g2(k+1));
41 -     % disp('End of Process')
42 - end
43
44 - N3 = 2520;
45 - delta_t3 = 10.0;
46 - h3 = zeros(1,N3);
47 - t3 = zeros(1,N3);
48 - h3(1) = 5.0;
49 - for k = 1:N3
50 -     g3(k) = -Cd*A*sqrt(2*g*h3(k))/(pi*(2*r*h3(k) - h3(k)^2));
51 -     % disp('Predictor')
52 -     x3(k+1) = h3(k) + g3(k)*delta_t3;
53 -     t3(k+1) = t3(k) + delta_t3;
54 -     g3(k+1) = -Cd*A*sqrt(2*g*x3(k+1))/(pi*(2*r*x3(k+1) - x3(k+1)^2));
55 -     % disp('Corrector')
56 -     h3(k+1) = h3(k) + delta_t3/2*(g3(k) + g3(k+1));
57 -     % disp('End of Process')
58 - end
59
60 - plot(t2,h2, t1,h1, t3,h3 )
61 - xlabel('Time t (seconds)'), ylabel('Water Height (m)')
62 - title('Problem 9.28: Scott Thomas')
63 - legend('\Delta t = 1000.0','\Delta t = 100.0','\Delta t = 10.0','Location', 'NorthEast')
64 - %axis([0 5 0 30])
65

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